

摘要

1961年, Piatetski-Shapiro[1]定义了 Siegel 域并证明了任何 Siegel 域全纯同构于有界域. 接着, Vinberg, Gindikin 和 Piatetski-Shapiro[2]于1963年证明了任何齐性有界域全纯同构于齐性 Siegel 域. 1976和1977年, 许以超[3]构造了一类特殊的齐性 Siegel 域, 即正规 Siegel 域 $D(V_N, F)$, 并且在[4]中证明了任何齐性 Siegel 域仿射等价于正规 Siegel 域. 1976年, 许以超还定出了全纯自同构群 $\text{Aut}(D(V_N, F))$ 的李代数 $\text{aut}(D(V_N, F))$ 和仿射自同构群 $\text{Aff}(D(V_N, F))$ 的生成元. 与此同时, Dorfmeister 给出了齐性有界域的一个代数实现和全纯自同构群, 但是该工作中一些全纯自同构群的存在条件并不清楚.

用 Cauchy-Szegö 核 $S(z, \bar{\xi})$, 华罗庚[6]构造了典型域上的形式泊松核 $P(z, \bar{z}, \xi, \bar{\xi}) = |S(z, \bar{\xi})|^2 / S(z, \bar{z})$, 并证明了形式泊松核是泊松核函数. 1965年, Koranyi 用李群理论证明了形式泊松核是对称 Siegel 域上的泊松核. 若 D 是一个不可分解的正规 Siegel 域, 许以超证明了形式泊松核是泊松核当且仅当 D 是对称 Siegel 域. 注意到对称域的 Silov 边界 $S(D)$ 在迷向子群的作用下是可递边界, 而对于非对称域的情形, 在迷向子群的作用下, Silov 边界 $S(D)$ 不是可递边界, 我们可以提出下述问题: 当 D 是非对称齐性 Siegel 域, 在 Bergman 度量下, Silov 边界 $S(D)$ 上的连续函数类到 Laplace-Beltrami 调和函数类的积分表示是什么?

为了考虑泊松积分, 我们需要得到正规 Siegel 域最大连通全纯自同构群 $\text{Aut}(D(V_N, F))$ 的生成元集和固定点 $(\sqrt{-1}v_0, 0)$ 的迷向子群 $\text{Iso}(D(V_N, F))$ 的生成元集的确切表示, 进而给出在迷向子群 $\text{Iso}(D(V_N, F))$ 作用下 Silov 边界所有轨道的确切表示. 本文给出了固定点 $(\sqrt{-1}v_0, 0)$ 的迷向子群 $\text{Iso}(D(V_N, F))$ 的生成元集并加以证明.

本文共分三章, 第一章简要介绍有关背景及本文的所要解决的问题; 第二章给出本文所用的一些符号及后面证明所需要的一些定义和定理; 第三章在许以超教授关于正规 Siegel 域所做工作的基础上, 通过求解一些常微分方程组, 给出一些单参数子群, 从而得到了正规 Siegel 域的迷向子群的生成元集.

关键词: 正规 Siegel 域, 全纯自同构群, 迷向子群, 单参数子群, 齐性 Siegel 域, 齐性有界域.

ABSTRACT

In 1961, Piatetski-Shapiro[1] defined Siegel domains and proved that any Siegel domain is holomorphically isomorphic to a bounded domain. Successively, in 1963, Vinberg, Gindikin and Piatetski-Shapiro[2] proved that any homogeneous bounded domain is holomorphically isomorphic to a homogeneous Siegel domain. In 1976 and 1977, Yichao Xu[3] constructed a class of special homogeneous Siegel domain, i. e. normal Siegel domain $D(V_N, F)$, and proved that any homogeneous Siegel domain is affine equivalent to a normal Siegel domain in [4]. Also in 1976, Xu determined the Lie algebra $\text{aut}(D(V_N, F))$ of the holomorphic automorphism group $\text{Aut}(D(V_N, F))$ and the generating elements of the affine automorphism group $\text{Aff}(D(V_N, F))$. At the same time, Dorfmeister gave an algebraic realization of a homogeneous bounded domain and the holomorphic automorphism group, but the existence condition of some holomorphic automorphisms in his work is not clear.

From Cauchy-Szegö kernel $S(z, \bar{\xi})$, Hua[6] constructed the formal Poisson kernel $P(z, \bar{z}, \xi, \bar{\xi}) = |S(z, \bar{\xi})|^2 / S(z, \bar{z})$ on a classical domain, and proved that the formal Poisson kernel is the Poisson kernel function. In 1965, Koranyi proved that the formal Poisson kernel is the Poisson kernel on the symmetric Siegel domains using the Lie group theory. When D is an indecomposable normal Siegel domain, Xu proved that a formal Poisson kernel is Poisson kernel if and only if D is a symmetric siegel domain. Note that the Silov boundary $S(D)$ of a symmetric domain is a transitive boundary acted by the isotropic subgroup, but in the case of non-symmetric domain, the Silov boundary $S(D)$ is not a transitive boundary acted by the isotropic subgroup. So we can pose the following problem: when D is a non-symmetric homogeneous Siegel domain, what is the integral representation from the continuous function class on Silov boundary $S(D)$ to the Laplace-Beltrami harmonic function class with respect to the Bergman metric on D ?

In order to consider the Poisson integral, we need to give the explicit expressions of the following two sets: one is the generating elements of the maximal connected holomorphic automorphism group $\text{Aut}(D(V_N, F))$ acting on the normal Siegel domains, the other is the generating elements of the isotropic subgroup $\text{Iso}(D(V_N, F))$ of the fixed point $(\sqrt{-1}v_0, 0)$. Particularly, we give the explicit expression of all orbits in the Silov boundary under the action by the isotropic subgroup $\text{Iso}(D(V_N, F))$. In this thesis, we will give the generating element set of the isotropic subgroup $\text{Iso}(D(V_N, F))$ of the fixed point $(\sqrt{-1}v_0, 0)$.

The thesis consists of three chapters. Chapter one gives a brief introduction to the relevant background and poses the problem which we will solve in this thesis. Chapter two introduces some necessary definitions and theorems needed for further arguments. In chapter three, based on professor Yichao Xu's work, we obtain the main results of this thesis: give some one parameter subgroups by solving some ordinary differential equations and get the generating element set of isotropic subgroup of normal Siegel domain.

Key words: normal Siegel domain, holomorphic automorphism group, one parameter subgroup, homogeneous Siegel domain, isotropic subgroup, homogeneous bounded domain.

第一章 主要结果

1959年, Piatetski-Shapiro 在研究对称有界域的自守函数时发现了 Siegel 域, 并在 1961 年 [1] 给出了其严格定义, 证明了任何 Siegel 域全纯同构于有界域. 接着, Piatetski-Shapiro 与 Vinberg, Gindikin 于 1963 年 [2] 证明了任何齐性有界域全纯同构于齐性 Siegel 域, 从而将齐性有界域的分类问题归结为齐性 Siegel 域的分类问题.

1976 和 1977 年, 许以超 [3] 构造了 \mathbb{C}^n 中一类特殊的齐性 Siegel 域, 即正规 Siegel 域 $D(V_N, F)$, 正规 Siegel 域是由满足一定条件的特殊矩阵集合 (N 矩阵组) 定义的, 并且在 [4] 中证明了任何齐性 Siegel 域仿射等价于正规 Siegel 域. 这样齐性 Siegel 域的分类就转化为正规 Siegel 域的分类, 进而转化为 N 矩阵组在等价意义下的分类. 但是这个分类问题至今还未被完全解决. 1976 年, 许以超还定出了正规 Siegel 域全纯自同构群 $\text{Aut}(D(V_N, F))$ 的李代数 $\text{aut}(D(V_N, F))$ 和仿射自同构群 $\text{Aff}(D(V_N, F))$ 的生成元, 并给出了 $D(V_N, F)$ 中一固定点 $p = (\sqrt{-1}v_0, 0)$, ($v_0 = (1, 0, 1, \dots, 0, 1)$) 的迷向子群 $\text{Iso}(D(V_N, F))$ 的李代数 $\text{iso}(D(V_N, F))$. 与此同时, Dorfmeister 给出了齐性有界域的一个代数实现和全纯自同构群, 但是该工作中一些全纯自同构群的存在条件并不清楚.

用 Cauchy-Szegö 核 $S(z, \bar{\xi})$, 华罗庚 [6] 构造了典型域上的形式泊松核 $P(z, \bar{z}, \xi, \bar{\xi}) = |S(z, \bar{\xi})|^2 / S(z, \bar{z})$, 并证明了形式泊松核是泊松核函数. 1965 年, Koranyi 用李群理论证明了形式泊松核是对称 Siegel 域上的泊松核. 若 D 是一个不可分解的正规 Siegel 域, 许以超证明了形式泊松核是泊松核当且仅当 D 是对称 Siegel 域. 注意到对称域的 Silov 边界 $S(D)$ 在迷向子群的作用下是可递边界, 而对于非对称域的情形, 在迷向子群的作用下, Silov 边界 $S(D)$ 不是可递边界, 我们可以提出下述问题: 当 D 是非对称齐性 Siegel 域, 在 Bergman 度量下, Silov 边界 $S(D)$ 上的连续函数类到 Laplace-Beltrami 调和函数类的积分表示是什么?

为了考虑泊松积分, 我们需要得到正规 Siegel 域最大连通全纯自同构群 $\text{Aut}(D(V_N, F))$ 的生成元集和固定点 $(\sqrt{-1}v_0, 0)$ 的迷向子群 $\text{Iso}(D(V_N, F))$ 的生成元集的确切表示, 进而给出在迷向子群 $\text{Iso}(D(V_N, F))$ 作用下 Silov 边界所有轨道的确切表示. 本文根据 \exp 映射下李代数和李群的对应关系以及单参数子群与李群的李代数的密切联系, 由李代数 $\text{iso}_p(D(V_N, F))$ 确定出正规 Siegel 域 $D(V_N, F)$ 的迷向子群 $\text{Iso}_p(D(V_N, F))$ 的生成元的集合.

注记 1: 本文从选题至行文到完成, 都经许以超先生悉心指导, 在此对许老师和师母吴老师在学业和生活上的关心和教导谨致衷心的感谢. 许, 吴两位老师的敬业精神和做人品格将永远是我学习的榜样.

注记 2: 本文初步定稿后经王天泽教授在文字上作了些修改, 在此对王老师几年来的帮助和关心表示感谢.

注记 3: 本文的写作参考了陈敏茹的硕士论文, 谨此致谢.

下面叙述本文的主要结果:

定理 正规 Siegel 域 $D(V_N, F)$ 中一固定点 p 的迷向子群 $\text{Iso}_p(D(V_N, F))$ 的生成元集可由下面的 (1)-(4) 给出:

(1) 李子群 $\exp(o(D(V_N, F)))$:

$$\begin{aligned} r_j &= s_j, \quad 1 \leq j \leq N, \\ w_{ij} &= z_{ij} O_{ij}, \quad 1 \leq i < j \leq N, \\ v_i &= u_i U_i, \quad 1 \leq i \leq N, \end{aligned}$$

其中 $O_{ij} \in O(n_{ij})$, $U_i \in U(m_i)$, 且满足

$$O'_{ik} A_{ij}^{tk} O_{jk} = \sum_{r=1}^{n_{ij}} (e_r O_{ij} e'_r) A_{ij}^{rk}, \quad \overline{U}_i' Q_{ij}^{(t)} U_j = \sum_{r=1}^{n_{ij}} (e_r O_{ij} e'_r) Q_{ij}^{(r)}.$$

(2) $\exp(\tilde{y}(D(V_N, F)))$, 它由 $\exp(\theta(X_{ij}^{(t)} - Z_{ij}^{(t)}))$ 生成, 其中 $\exp(\theta(X_{ij}^{(t)} - Z_{ij}^{(t)}))$ 为:

$$\begin{aligned} r_p &= s_p, \quad p \neq i, j, \\ r_i &= \left(\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_i + \left(-\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_j + \sin 2\theta z_{ij}^{(t)}, \\ r_j &= \left(-\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_i + \left(\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_j - \sin 2\theta z_{ij}^{(t)}, \\ w_{ij}^{(s)} &= z_{ij}^{(s)}, \quad s \neq t, \\ w_{ij}^{(t)} &= -\frac{1}{2} \sin 2\theta s_i + \frac{1}{2} \sin 2\theta s_j + \cos 2\theta z_{ij}^{(t)}, \\ w_{pi} &= z_{pi} \cos \theta + z_{pj} \sum_s A_{pi}^{sj} e'_s e_s \sin \theta, \quad p < i, \\ w_{pj} &= -z_{pi} \sum_s e'_s e_s (A_{pi}^{sj})' \sin \theta + z_{pj} \cos \theta, \quad p < i, \\ w_{ip} &= z_{ip} \cos \theta + z_{pj} \sum_s (A_{ip}^{sj})' e'_s e_s \sin \theta, \quad i < p < j, \\ w_{pj} &= -z_{ip} \sum_s e'_s e_s A_{ip}^{sj} \sin \theta + z_{pj} \cos \theta, \quad i < p < j, \\ w_{ip} &= z_{ip} \cos \theta + z_{jp} (A_{ij}^{tp})' \sin \theta, \quad p > j, \\ w_{jp} &= -z_{ip} A_{ij}^{tp} \sin \theta + z_{jp} \cos \theta, \quad p > j, \\ v_p &= u_p, \quad p \neq i, j, \\ v_i &= u_i \cos \theta + u_j \overline{(Q_{ij}^{(t)})'} \sin \theta, \\ v_j &= -u_i Q_{ij}^{(t)} \sin \theta + u_j \cos \theta. \end{aligned}$$

(3) $\exp(\tilde{L}_1)$, 它由下面两类单参数子群生成.

(3-i) $\exp(\theta(Y_i^{(t)} - \tilde{P}_i^{(t)}))$:

$$\begin{aligned}
r_i &= -\frac{2}{f(\theta)} - \sqrt{-1}, \\
v_i &= \frac{\sqrt{-1}\sqrt{c-1} \cos(2\theta + c') e_t + c_2}{f(\theta)}, \\
w_{pi} &= \frac{1}{f(\theta)} \sum_s \frac{\sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'})}{\sin c_{pi}^{(s)'}} f(0) z_{pi} U_{pi} e'_s e_s \bar{U}_{pi}', \quad p < i, \\
w_{ip} &= \frac{1}{f(\theta)} \sum_r \frac{\sin(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'})}{\sin c_{ip}^{(r)'}} f(0) z_{ip} U_{ip} e'_r e_r \bar{U}_{ip}', \quad p > i, \\
r_p &= \sum_{s,r} \frac{2\sqrt{-1} f^2(0) z_{pi} U_{pi} E_{ss} \bar{U}_{pi}' \bar{U}_{pi} E_{rr} U_{pi}' z'_{pi}}{\sin c_{pi}^{(s)' } \sin c_{pi}^{(r)' }} \\
&\quad \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'}) \sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) d\theta \right) d\theta, \quad p < i, \\
r_p &= \sum_{s,r} \frac{2\sqrt{-1} f^2(0) z_{ip} U_{ip} E_{ss} \bar{U}_{ip}' \bar{U}_{ip} E_{rr} U_{ip}' z'_{ip}}{\sin c_{ip}^{(s)' } \sin c_{ip}^{(r)' }} \\
&\quad \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\mu_{ip}^{(s)}} \theta + c_{ip}^{(s)'}) \sin(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'}) d\theta \right) d\theta, \quad p > i, \\
v_p &= \sum_{s,r} f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' E_{st} (Q_{pi}^{(s)})' \int \frac{\sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'})}{\sin c_{pi}^{(r)' } f(\theta)} d\theta - \frac{1}{2} \sum_{s,r} f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' e'_s \\
&\quad \cdot \left(\int \frac{\sqrt{2\lambda_{pi}^{(r)}} \cos(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) f(\theta) - \sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) f'(\theta)}{\sin c_{pi}^{(r)' } f^2(\theta)} \right. \\
&\quad \left. (\sqrt{-1}\sqrt{c-1} \cos(2\theta + c') e_t + c_2) d\theta \right) (Q_{pi}^{(s)})', \quad p < i, \\
v_p &= \sum_{s,r} f(0) z_{ip} U_{ip} E_{rr} \bar{U}_{ip}' E_{st} Q_{ip}^{(s)} \int \frac{\sin(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'})}{\sin c_{ip}^{(r)' } f(\theta)} d\theta - \frac{1}{2} \sum_{s,r} f(0) z_{ip} U_{ip} E_{rr} \bar{U}_{ip}' e'_s \\
&\quad \cdot \left(\int \frac{\sqrt{2\mu_{ip}^{(r)}} \cos(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'}) f(\theta) - \sin(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'}) f'(\theta)}{\sin c_{ip}^{(r)' } f^2(\theta)} \right. \\
&\quad \left. (\sqrt{-1}\sqrt{c-1} \cos(2\theta + c') e_t + c_2) d\theta \right) Q_{ip}^{(s)}, \quad p > i, \\
w_{lp} &= \sum_{s,r,u,h} \frac{2\sqrt{-1} f^2(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' e'_s z_{li} U_{li} E_{hh} \bar{U}_{li}' A_{ip}^{ui} e'_s e_u}{\sin c_{pi}^{(r)' } \sin c_{li}^{(h)' }} \\
&\quad \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) \sin(\sqrt{2\lambda_{li}^{(h)}} \theta + c_{li}^{(h)'}) d\theta \right) d\theta, \quad l < p < i,
\end{aligned}$$

$$w_{lp} = \sum_{s,r,u} \frac{2\sqrt{-1}f^2(0)z_{li}U_{li}E_{rr}\bar{U}_{li}'e'_s z_{ip}U_{ip}E_{uu}\bar{U}_{ip}'(A_{li}^{sp})'}{\sin c_{li}^{(r)} \sin c_{ip}^{(u)'}} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{li}^{(r)}}\theta + c_{li}^{(r)'}) \sin(\sqrt{2\mu_{ip}^{(u)}}\theta + c_{ip}^{(u)'}) d\theta \right) d\theta, \quad l < i < p,$$

$$w_{lp} = \sum_{s,r,u} \frac{2\sqrt{-1}f^2(0)z_{il}U_{il}E_{rr}\bar{U}_{il}'e'_s z_{ip}U_{ip}E_{uu}\bar{U}_{ip}'A_{il}^{sp}}{\sin c_{il}^{(r)' } \sin c_{ip}^{(u)'}} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\mu_{il}^{(r)}}\theta + c_{il}^{(r)'}) \sin(\sqrt{2\mu_{ip}^{(u)}}\theta + c_{ip}^{(u)'}) d\theta \right) d\theta, \quad i < l < p.$$

其中

$$c = \frac{4\sqrt{-1}s_i - 4u_i^{(t)2}}{(s_i + \sqrt{-1})^2}, \quad c' = \arctg \frac{\sqrt{-1} - s_i}{2u_i^{(t)}}, \quad f(\theta) = \sqrt{c-1} \sin(2\theta + c') + \sqrt{-1};$$

在 v_i 的表达式中, $c_2 = \frac{-2u_i + 2u_i^{(t)}e_t}{s_i + \sqrt{-1}}$;

在 w_{pi} 的表达式中, 酉矩阵 U_{pi} 使 Hermite 矩阵 $H = \sum_{s,r} e'_s e_t (Q_{pi}^{(s)})' Q_{pi}^{(r)} e'_t e_r$ 对角化, $\lambda_{pi}^{(s)}$, $s = 1, \dots, n_{pi}$ 为 H 的特征值,

$$c_{pi}^{(s)'} = \arctg \frac{\sqrt{2\lambda_{pi}^{(s)}} f(0) z_{pi} U_{pi} e'_s}{(\sqrt{-1} f(0) (\sum_s (s_i + \sqrt{-1}) u_p Q_{pi}^{(s)} e'_t e_s + \sum_{s,r} z_{pi}^{(s)} u_i (Q_{pi}^{(r)})' Q_{pi}^{(s)} e'_t e_r) + f'(0) z_{pi}) U_{pi} e'_s};$$

在 w_{ip} 的表达式中, 酉矩阵 U_{ip} 使 Hermite 矩阵 $M = \sum_{s,r} e'_s e_t Q_{ip}^{(s)} (Q_{ip}^{(r)})' e'_t e_r$ 对角化, $\mu_{ip}^{(r)}$, $r = 1, \dots, n_{ip}$ 为 M 的特征值,

$$c_{ip}^{(r)'} = \arctg \frac{\sqrt{2\mu_{ip}^{(r)}} f(0) z_{ip} U_{ip} e'_r}{(\sqrt{-1} f(0) (\sum_s (s_i + \sqrt{-1}) u_p (Q_{ip}^{(s)})' e'_t e_s + \sum_{s,r} z_{ip}^{(s)} u_i Q_{ip}^{(r)} (Q_{ip}^{(s)})' e'_t e_r) + f'(0) z_{ip}) U_{ip} e'_r};$$

在 $r_p (p < i)$ 的表达式中, 待定参数由初值 $r_p(0) = s_p$, $\frac{dr_p}{d\theta}(0) = 2\sqrt{-1} \sum_s z_{pi}^{(s)} u_p Q_{pi}^{(s)} e'_t$ 确定;

在 $r_p (p > i)$ 的表达式中, 待定参数由初值 $r_p(0) = s_p$, $\frac{dr_p}{d\theta}(0) = 2\sqrt{-1} \sum_s z_{ip}^{(s)} u_p (Q_{ip}^{(s)})' e'_t$ 确定;

在 $v_p (p < i)$ 的表达式中, 待定参数由初值 $v_p(0) = u_p$ 确定;

在 $v_p (p > i)$ 的表达式中, 待定参数由初值 $v_p(0) = u_p$ 确定;

在 $w_{lp} (l < p < i)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$, $\frac{dw_{lp}}{d\theta}(0) = \sqrt{-1} \sum_{s,u} [u_p Q_{pi}^{(s)} e'_t z_{li} A_{ip}^{ui} e'_s e_u + u_i Q_{li}^{(s)} e'_t e_s A_{ip}^{ui} z_{pi}' e_u]$ 确定;

在 $w_{lp}(i < l < p)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,
 $\frac{dw_{lp}}{d\theta}(0) = \sqrt{-1} \sum_s u_l Q_{li}^{(s)} e'_t z_{lp} (A_{li}^{sp})' + \sqrt{-1} \sum_{s,u} z_{li}^{(u)} u_p (Q_{ip}^{(s)})' e'_t e_s (A_{li}^{up})'$ 确定;

在 $w_{lp}(i < l < p)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,
 $\frac{dw_{lp}}{d\theta}(0) = \sqrt{-1} \sum_s u_l (Q_{il}^{(s)})' e'_t z_{lp} A_{il}^{sp} + \sqrt{-1} \sum_{s,u} z_{il}^{(u)} u_p (Q_{ip}^{(s)})' e'_t e_s A_{il}^{up}$ 确定.

(3-ii) $\exp(\theta(\tilde{Y}_i^{(t)} + P_i^{(t)}))$:

$$r_i = -\frac{2}{f(\theta)} - \sqrt{-1},$$

$$v_i = \frac{-\sqrt{c-1} \cos(2\theta + c') e_t + c_2}{f(\theta)},$$

$$w_{pi} = \frac{1}{f(\theta)} \sum_s \frac{\sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'})}{\sin c_{pi}^{(s)'}} f(0) z_{pi} U_{pi} e'_s e_s \bar{U}_{pi}', \quad p < i,$$

$$w_{ip} = \frac{1}{f(\theta)} \sum_r \frac{\sin(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'})}{\sin c_{ip}^{(r)'}} f(0) z_{ip} U_{ip} e'_r e_r \bar{U}_{ip}', \quad p > i,$$

$$r_p = \sum_{s,r} \frac{2\sqrt{-1} f^2(0) z_{pi} U_{pi} E_{ss} \bar{U}_{pi}' \bar{U}_{pi} E_{rr} U_{pi}' z'_{pi}}{\sin c_{pi}^{(s)' } \sin c_{pi}^{(r)' }} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'}) \sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) d\theta \right) d\theta, \quad p < i,$$

$$r_p = \sum_{s,r} \frac{2\sqrt{-1} f^2(0) z_{ip} U_{ip} E_{ss} \bar{U}_{ip}' \bar{U}_{ip} E_{rr} U_{ip}' z'_{ip}}{\sin c_{ip}^{(s)' } \sin c_{ip}^{(r)' }} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\mu_{ip}^{(s)}} \theta + c_{ip}^{(s)'}) \sin(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'}) d\theta \right) d\theta, \quad p > i,$$

$$v_p = \sqrt{-1} \sum_{s,r} f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' E_{st} (Q_{pi}^{(s)})' \int \frac{\sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'})}{\sin c_{pi}^{(r)' } f(\theta)} d\theta - \sum_{s,r} \frac{f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' e'_s}{2} \cdot \left(\int \frac{\sqrt{2\lambda_{pi}^{(r)}} \cos(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) f(\theta) - \sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) f'(\theta)}{\sin c_{pi}^{(r)' } f^2(\theta)} \right. \\ \left. (-\sqrt{c-1} \cos(2\theta + c') e_t + c_2) d\theta \right) (Q_{pi}^{(s)})', \quad p < i,$$

$$v_p = \sqrt{-1} \sum_{s,r} f(0) z_{ip} U_{ip} E_{rr} \bar{U}_{ip}' E_{st} Q_{ip}^{(s)} \int \frac{\sin(\sqrt{2\mu_{ip}^{(r)}} \theta + c_{ip}^{(r)'})}{\sin c_{ip}^{(r)' } f(\theta)} d\theta - \sum_{s,r} \frac{f(0) z_{ip} U_{ip} E_{rr} \bar{U}_{ip}' e'_s}{2}$$

$$\begin{aligned}
& \cdot \left(\int \frac{\sqrt{2\mu_{ip}^{(r)}} \cos(\sqrt{2\mu_{ip}^{(r)}}\theta + c_{ip}^{(r)'}) f(\theta) - \sin(\sqrt{2\mu_{ip}^{(r)}}\theta + c_{ip}^{(r)'}) f'(\theta)}{\sin c_{ip}^{(r)'}} f^2(\theta) \right. \\
& \quad \left. (-\sqrt{c-1} \cos(2\theta + c') e_t + c_2) d\theta \right) Q_{ip}^{(s)}, \quad p > i, \\
w_{lp} &= \sum_{s,r,u,h} \frac{2\sqrt{-1} f^2(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' e_s' z_{li} U_{li} E_{hh} \bar{U}_{li}' A_{ip}^{ui} e_s' e_u}{\sin c_{pi}^{(r)'}} \sin c_{li}^{(h)'}} \\
& \quad \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) \sin(\sqrt{2\lambda_{li}^{(h)}}\theta + c_{li}^{(h)'}) d\theta \right) d\theta, \quad l < p < i, \\
w_{lp} &= \sum_{s,r,u} \frac{2\sqrt{-1} f^2(0) z_{li} U_{li} E_{rr} \bar{U}_{li}' e_s' z_{ip} U_{ip} E_{uu} \bar{U}_{ip}' (A_{li}^{sp})'}{\sin c_{li}^{(r)'}} \sin c_{ip}^{(u)'}} \\
& \quad \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{li}^{(r)}}\theta + c_{li}^{(r)'}) \sin(\sqrt{2\mu_{ip}^{(u)}}\theta + c_{ip}^{(u)'}) d\theta \right) d\theta, \quad l < i < p, \\
w_{lp} &= \sum_{s,r,u} \frac{2\sqrt{-1} f^2(0) z_{il} U_{il} E_{rr} \bar{U}_{il}' e_s' z_{ip} U_{ip} E_{uu} \bar{U}_{ip}' A_{il}^{sp}}{\sin c_{li}^{(r)'}} \sin c_{ip}^{(u)'}} \\
& \quad \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\mu_{il}^{(r)}}\theta + c_{il}^{(r)'}) \sin(\sqrt{2\mu_{ip}^{(u)}}\theta + c_{ip}^{(u)'}) d\theta \right) d\theta, \quad i < l < p.
\end{aligned}$$

其中

$$c = \frac{4\sqrt{-1}s_i + 4u_i^{(t)^2}}{(s_i + \sqrt{-1})^2}, \quad c' = \operatorname{arctg} \frac{1 + \sqrt{-1}s_i}{2u_i^{(t)}}, \quad f(\theta) = \sqrt{c-1} \sin(2\theta + c') + \sqrt{-1};$$

在 v_i 的表达式中, $c_2 = \frac{-2u_i + 2u_i^{(t)} e_t}{s_i + \sqrt{-1}}$;

在 w_{pi} 的表达式中, 酉矩阵 U_{pi} 使 Hermite 矩阵 $H = \sum_{s,r} e_s' e_t \overline{(Q_{pi}^{(s)})'} Q_{pi}^{(r)} e_t' e_r$ 对角化, $\lambda_{pi}^{(s)}$, $s = 1, \dots, n_{pi}$ 为 H 的特征值,

$$c_{pi}^{(s)'} = \operatorname{arctg} \frac{\sqrt{2\lambda_{pi}^{(s)}} f(0) z_{pi} U_{pi} e_s'}{(f(0) (\sum_s (s_i + \sqrt{-1}) u_p \overline{(Q_{pi}^{(s)})'} e_t' e_s + \sum_{s,r} z_{pi}^{(s)} u_i \overline{(Q_{pi}^{(r)})'} Q_{pi}^{(s)} e_t' e_r) + f'(0) z_{pi}) U_{pi} e_s'}$$

在 w_{ip} 的表达式中, 酉矩阵 U_{ip} 使 Hermite 矩阵 $M = \sum_{s,r} e_s' e_t Q_{ip}^{(s)} \overline{(Q_{ip}^{(r)})'} e_t' e_r$ 对角化, $\mu_{ip}^{(r)}$, $r = 1, \dots, n_{ip}$ 为 M 的特征值,

$$c_{ip}^{(r)'} = \operatorname{arctg} \frac{\sqrt{2\mu_{ip}^{(r)}} f(0) z_{ip} U_{ip} e_r'}{(f(0) (\sum_s (s_i + \sqrt{-1}) u_p \overline{(Q_{ip}^{(s)})'} e_t' e_s + \sum_{s,r} z_{ip}^{(s)} u_i \overline{(Q_{ip}^{(r)})'} Q_{ip}^{(s)} e_t' e_r) + f'(0) z_{ip}) U_{ip} e_r'}$$

在 $r_p(p < i)$ 的表达式中, 待定参数由初值 $r_p(0) = s_p, \frac{dr_p}{d\theta}(0) = 2 \sum_s z_{pi}^{(s)} u_p Q_{pi}^{(s)} e'_t$ 确定;

在 $r_p(p > i)$ 的表达式中, 待定参数由初值 $r_p(0) = s_p, \frac{dr_p}{d\theta}(0) = 2 \sum_s z_{ip}^{(s)} u_p \overline{Q_{ip}^{(s)'}}$ 确定;

在 $v_p(p < i)$ 的表达式中, 待定参数由初值 $v_p(0) = u_p$ 确定;

在 $v_p(p > i)$ 的表达式中, 待定参数由初值 $v_p(0) = u_p$ 确定;

在 $w_{lp}(l < p < i)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,

$$\frac{dw_{lp}}{d\theta}(0) = \sum_{s,u} [u_p Q_{pi}^{(s)} e'_t z_{li} A_{lp}^{ui} e'_s e_u + u_l Q_{li}^{(s)} e'_t e_s A_{lp}^{ui} z'_{pi} e_u] \text{ 确定};$$

在 $w_{lp}(i < l < p)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,

$$\frac{dw_{lp}}{d\theta}(0) = \sum_s u_l Q_{li}^{(s)} e'_t z_{ip} (A_{li}^{sp})' + \sum_{s,u} z_{li}^{(u)} u_p \overline{Q_{ip}^{(s)'}} e'_t e_s (A_{li}^{up})' \text{ 确定};$$

在 $w_{lp}(i < l < p)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,

$$\frac{dw_{lp}}{d\theta}(0) = \sum_s u_l \overline{Q_{il}^{(s)'}} e'_t z_{ip} A_{il}^{sp} + \sum_{s,u} z_{il}^{(u)} u_p \overline{Q_{ip}^{(s)'}} e'_t e_s A_{il}^{up} \text{ 确定}.$$

(4) $\exp(\tilde{L}_2)$, 它由下面两类单参数子群生成.

(4-i) $\exp(\arctg \theta (B_i + \frac{\theta}{\partial s_i}))$:

$$r_i = \frac{s_i + \theta}{1 - s_i \theta},$$

$$r_p = s_p + \frac{\theta}{1 - s_i \theta} z_{pi} z'_{pi}, \quad p < i,$$

$$r_p = s_p + \frac{\theta}{1 - s_i \theta} z_{ip} z'_{ip}, \quad p > i,$$

$$w_{pi} = \frac{\sqrt{1 + \theta^2}}{1 - s_i \theta} z_{pi}, \quad p < i,$$

$$w_{ip} = \frac{\sqrt{1 + \theta^2}}{1 - s_i \theta} z_{ip}, \quad p > i,$$

$$w_{kp} = z_{kp} + \sum_s \frac{\theta}{1 - s_i \theta} z_{ki} A_{kp}^{si} z'_{pi} e_s, \quad k < p < i,$$

$$w_{kp} = z_{kp} + \sum_s \frac{\theta}{1 - s_i \theta} z_{ki}^{(s)} z_{ip} (A_{ki}^{sp})', \quad k < i < p,$$

$$w_{kp} = z_{kp} + \sum_s \frac{\theta}{1 - s_i \theta} z_{ik}^{(s)} z_{ip} A_{ik}^{sp},$$

$$v_i = \frac{\sqrt{1 + \theta^2}}{1 - s_i \theta} u_i,$$

$$v_p = u_p + \sum_s \frac{\theta}{1 - s_i \theta} z_{pi}^{(s)} u_i \overline{Q_{pi}^{(s)'}}, \quad p < i,$$

$$v_p = u_p + \sum_s \frac{\theta}{1 - s_i \theta} z_{ip}^{(s)} u_i Q_{ip}^{(s)}, \quad p > i.$$

$$(4\text{-ii}) \quad \exp\left(\theta(T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}})\right):$$

$$r_i = s_i \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi},$$

$$r_j = s_j \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi},$$

$$w_{ij} = w_{ij}^{(t)} e_t + \sum_{s \neq t} w_{ij}^{(s)} e_s = \frac{\sqrt{2}(1-A^2) \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \sum_{s \neq t} z_{ij}^{(s)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}$$

$$w_{pi}^{(u)} = z_{pi}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{pi}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{pi}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pi}, \quad p < i,$$

$$w_{pj}^{(u)} = z_{pj}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{pj}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{pj}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pj}, \quad p < i,$$

$$w_{ip}^{(u)} = z_{ip}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{ip}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{ip}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{ip}, \quad i < p < j,$$

$$w_{pj}^{(u)} = z_{pj}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{pj}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{pj}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pj}, \quad i < p < j,$$

$$w_{ip}^{(u)} = z_{ip}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{ip}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{ip}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{ip}, \quad p > j,$$

$$w_{jp}^{(u)} = z_{jp}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{jp}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{jp}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{jp}, \quad p > j,$$

$$v_i^{(u)} = d_i^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_i^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_i^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, m_i,$$

$$v_j^{(u)} = d_j^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_j^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_j^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, m_j,$$

$$\tau_p = g_0(\varphi) + a_0, \quad p < i,$$

$$\tau_p = g_1(\varphi) + a_1, \quad i < p < j,$$

$$\tau_p = g_2(\varphi) + a_2, \quad p > j,$$

$$w_{pk} = g_3(\varphi) + a_3, \quad p < k < i,$$

$$w_{pk} = g_4(\varphi) + a_4, \quad p < i < k < j,$$

$$w_{pk} = g_5(\varphi) + a_5, \quad p < i < j < k,$$

$$w_{pk} = g_6(\varphi) + a_6, \quad i < p < k < j,$$

$$w_{pk} = g_7(\varphi) + a_7, \quad i < p < j < k,$$

$$\begin{aligned}
w_{pk} &= g_8(\varphi) + a_8, \quad j < p < k, \\
v_p &= g_9(\varphi) + a_9, \quad p < i, \\
v_p &= g_{10}(\varphi) + a_{10}, \quad i < p < j, \\
v_p &= g_{11}(\varphi) + a_{11}, \quad p > j.
\end{aligned}$$

其中

$$\begin{aligned}
c &= \frac{\sum_{s \neq t} z_{ij}^{(s)2} - s_i s_j}{(s_i s_j - z_{ij} z_{ij}' - 2)^2}, \\
c' &= \frac{1}{\sqrt{2}} \operatorname{arctg} \sqrt{2} \frac{\sqrt{1-8c} + \sqrt{1-8c-4cz_{ij}^{(t)2}}}{1 - \sqrt{1-8cz_{ij}^{(t)}}}, \quad A = \frac{1 - \sqrt{1-8c}}{2\sqrt{2c}}, \\
\varphi &= \theta + c',
\end{aligned}$$

在 $w_{pi}^{(u)}$ ($p < i$) 的表达式中,

$$d_{pi}^{(u)'} = \operatorname{arctg} \left(\frac{[s_i \sum_s z_{pj} A_{pi}^{sj} e_t' e_s + \sum_{s,r} z_{pi}^{(s)} z_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e_t' e_r] e_u'}{\sqrt{2} z_{pi}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{pj}^{(u)}$ ($p < i$) 的表达式中,

$$d_{pj}^{(u)'} = \operatorname{arctg} \left(\frac{[s_j \sum_s z_{pi}^{(s)} e_t (A_{pi}^{sj})' + \sum_s z_{pj} A_{pi}^{sj} e_t' z_{ij} (A_{pi}^{sj})'] e_u'}{\sqrt{2} z_{pj}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{ip}^{(u)}$ ($i < p < j$) 的表达式中,

$$d_{ip}^{(u)'} = \operatorname{arctg} \left(\frac{[s_i \sum_s e_t A_{ip}^{sj} z_{pj}' e_s + \sum_{s,r} z_{ip}^{(s)} z_{ij} A_{ip}^{rj} (A_{ip}^{sj})' e_t' e_r] e_u'}{\sqrt{2} z_{ip}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{pj}^{(u)}$ ($i < p < j$) 的表达式中,

$$d_{pj}^{(u)'} = \operatorname{arctg} \left(\frac{[s_j \sum_s z_{ip}^{(s)} e_t A_{ip}^{sj} + \sum_s e_t A_{ip}^{sj} z_{pj}' z_{ij} A_{ip}^{sj}] e_u'}{\sqrt{2} z_{pj}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{ip}^{(u)}$ ($p > j$) 的表达式中,

$$d_{ip}^{(u)'} = \operatorname{arctg} \left(\frac{[s_i z_{jp} (A_{ij}^{tp})' + \sum_s z_{ij}^{(s)} z_{ip} A_{ij}^{tp} (A_{ij}^{sp})'] e_u'}{\sqrt{2} z_{ip}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{jp}^{(u)}$ ($p > j$) 的表达式中,

$$d_{jp}^{(u)'} = \operatorname{arctg} \left(\frac{[s_j z_{ip} A_{ij}^{tp} + \sum_s z_{ij}^{(s)} z_{jp} (A_{ij}^{tp})' A_{ij}^{sp}] e_u'}{\sqrt{2} z_{jp}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $v_i^{(u)}$ 的表达式中,

$$d_i^{(u)'} = \operatorname{arctg} \left(\frac{[s_i u_j (Q_{ij}^{(t)}) + \sum_s z_{ij}^{(s)} u_i Q_{ij}^{(t)} (Q_{ij}^{(s)})] e_u'}{\sqrt{2} u_i^{(u)}} - \frac{(1 - A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $v_j^{(u)}$ 的表达式中,

$$d_j^{(u)'} = \operatorname{arctg} \left(\frac{[s_j u_i Q_{ij}^{(t)} + \sum_s z_{ij}^{(s)} u_j (Q_{ij}^{(t)}) Q_{ij}^{(s)}] e_u'}{\sqrt{2} u_j^{(u)}} - \frac{(1 - A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $r_p (p < i)$ 的表达式中,

$$\begin{aligned} g_0(\varphi) = & \frac{1}{\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{pi}^{(s)'} \cos \sqrt{2}d_{pj}^{(r)'}}{A^3} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pi}^{(s)'} + d_{pj}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(s)'} \sin \sqrt{2}d_{pj}^{(r)'}}{A} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \\ & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right] z_{pi}^{(s)} z_{pj}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(s)'}) \sin \sqrt{2}(c' + d_{pj}^{(r)'})} e_r A_{pi}^{sj} e_t', \end{aligned}$$

$$a_0 = s_p - g_0(c');$$

在 $r_p (i < p < j)$ 的表达式中,

$$\begin{aligned} g_1(\varphi) = & \frac{1}{\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{pj}^{(r)'}}{A^3} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{pj}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{pj}^{(r)'}}{A} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \\ & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right] z_{ip}^{(s)} z_{pj}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{pj}^{(r)'})} e_r (A_{ip}^{sj})' e_t', \end{aligned}$$

$$a_1 = s_p - g_1(c');$$

在 $r_p (p > j)$ 的表达式中,

$$\begin{aligned} g_2(\varphi) = & \frac{1}{\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{jp}^{(r)'}}{A^3} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{jp}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{jp}^{(r)'}}{A} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \\ & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right] z_{ip}^{(s)} z_{jp}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{jp}^{(r)'})} e_s A_{ij}^{tp} e_r', \end{aligned}$$

$$a_2 = s_p - g_2(c');$$

在 $w_{pk}(p < k < i)$ 的表达式中,

$$\begin{aligned}
g_3(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u,v} \left[\frac{\cos \sqrt{2}d_{pj}^{(u)'} \cos \sqrt{2}d_{ki}^{(v)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(u)'} + d_{ki}^{(v)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \\
& + \left. \frac{\sin \sqrt{2}d_{pj}^{(u)'} \sin \sqrt{2}d_{ki}^{(v)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right] \\
& z_{pj}^{(u)} z_{ki}^{(v)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(u)'}) \sin \sqrt{2}(c' + d_{ki}^{(v)'})} e_u A_{pi}^{sj} e_t' e_s A_{pk}^{ri} e_v' e_r \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r,u,v} \left[\frac{\cos \sqrt{2}d_{kj}^{(u)'} \cos \sqrt{2}d_{pi}^{(v)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{kj}^{(u)'} + d_{pi}^{(v)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \\
& + \left. \frac{\sin \sqrt{2}d_{kj}^{(u)'} \sin \sqrt{2}d_{pi}^{(v)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right] \\
& z_{kj}^{(u)} z_{pi}^{(v)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{kj}^{(u)'}) \sin \sqrt{2}(c' + d_{pi}^{(v)'})} e_u A_{ki}^{sj} e_t' e_s (A_{pk}^{ri})' e_v' e_r,
\end{aligned}$$

$$a_3 = z_{pk} - g_3(c');$$

在 $w_{pk}(p < i < k < j)$ 的表达式中,

$$\begin{aligned}
g_4(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pi}^{(r)'} \cos \sqrt{2}d_{kj}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pi}^{(r)'} + d_{kj}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(r)'} \sin \sqrt{2}d_{kj}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pi}^{(r)} z_{kj}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(r)'}) \sin \sqrt{2}(c' + d_{kj}^{(u)'})} e_t A_{ik}^{sj} e_u' e_s (A_{pi}^{rk})' \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_{ik}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi
\end{aligned}$$

$$+ \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_r A_{pi}^{sj} e'_t e_u (A_{pi}^{sk})',$$

$$a_4 = z_{pk} - g_4(c');$$

在 $w_{pk}(p < i < j < k)$ 的表达式中,

$$\begin{aligned} g_5(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{pi}^{(s)'}}{A^3} \cos \sqrt{2}d_{jk}^{(r)'} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pi}^{(s)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(s)'}}{A} \frac{\sin \sqrt{2}d_{jk}^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pi}^{(s)} z_{jk}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(s)'}) \sin \sqrt{2}(c' + d_{jk}^{(r)'})} e_r (A_{ij}^{tk})' (A_{pi}^{sk})' \\ & + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'}}{A^3} \cos \sqrt{2}d_{ik}^{(u)' } (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pj}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'}}{A} \frac{\sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_r A_{pi}^{sj} e'_t e_u (A_{pi}^{sk})', \end{aligned}$$

$$a_5 = z_{pk} - g_5(c');$$

在 $w_{pk}(i < p < k < j)$ 的表达式中,

$$\begin{aligned} g_6(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{ip}^{(r)'}}{A^3} \cos \sqrt{2}d_{kj}^{(u)' } (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{ip}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(r)'}}{A} \frac{\sin \sqrt{2}d_{kj}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{ip}^{(r)} z_{kj}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(r)'}) \sin \sqrt{2}(c' + d_{kj}^{(u)'})} e_t A_{ik}^{sj} e'_u e_s A_{ip}^{rk} \\ & + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'}}{A^3} \cos \sqrt{2}d_{ik}^{(u)' } (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pj}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'}}{A} \frac{\sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_t A_{ip}^{sj} e'_r e_u A_{ip}^{sk}, \end{aligned}$$

$$a_6 = z_{pk} - g_6(c');$$

在 $w_{pk}(i < p < j < k)$ 的表达式中,

$$\begin{aligned}
g_7(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{jk}^{(r)'}}{A^3} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
& + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{jk}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{jk}^{(r)'}}{A} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \right. \\
& \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \Big] z_{ip}^{(s)} z_{jk}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{jk}^{(r)'})} e_r (A_{ij}^{tk})' A_{ip}^{sk} \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_{ik}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_{ik}^{(u)'}}{A} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \right. \\
& \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \Big] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_t A_{ip}^{sj} e_r' e_u A_{ip}^{sk},
\end{aligned}$$

$$a_7 = z_{pk} - g_7(c');$$

在 $w_{pk}(j < p < k)$ 的表达式中,

$$\begin{aligned}
g_8(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{jp}^{(r)'} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
& + \frac{\sin \sqrt{2}(d_{jp}^{(r)'} + d_{ik}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{jp}^{(r)'} \sin \sqrt{2}d_{ik}^{(u)'}}{A} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \right. \\
& \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \Big] z_{jp}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{jp}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_r (A_{ij}^{tp})' e_s' e_u A_{ip}^{sk} \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{jk}^{(r)'}}{A^3} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
& + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{jk}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{jk}^{(r)'}}{A} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \right. \\
& \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \Big] z_{ip}^{(s)} z_{jk}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{jk}^{(r)'})} e_r (A_{ij}^{tk})' A_{ip}^{sk},
\end{aligned}$$

$$a_8 = z_{pk} - g_8(c');$$

在 $v_p (p < i)$ 的表达式中,

$$\begin{aligned}
g_9(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_i^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_i^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_i^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pj}^{(r)} u_i^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_i^{(u)'})} e_r A_{pi}^{sj} e'_t e_u \overline{Q_{pi}^{(s)'}} \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{pi}^{(s)'} \cos \sqrt{2}d_j^{(r)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pi}^{(s)'} + d_j^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(s)'} \sin \sqrt{2}d_j^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pi}^{(s)} u_j^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(s)'}) \sin \sqrt{2}(c' + d_j^{(r)'})} e_r \overline{Q_{ij}^{(t)'}} \overline{Q_{pi}^{(s)'}} ,
\end{aligned}$$

$$a_9 = u_p - g_9(c');$$

在 $v_p (i < p < j)$ 的表达式中,

$$\begin{aligned}
g_{10}(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_i^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_i^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_i^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pj}^{(r)} u_i^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_i^{(u)'})} e_t A_{ip}^{sj} e'_r e_u Q_{ip}^{(s)} \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_j^{(r)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_j^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_j^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{ip}^{(s)} u_j^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_j^{(r)'})} e_r \overline{Q_{ij}^{(t)'}} Q_{ip}^{(s)} ,
\end{aligned}$$

$$a_{10} = u_p - g_{10}(c');$$

在 $v_p(p > j)$ 的表达式中,

$$\begin{aligned}
g_{11}(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{jp}^{(r)'} \cos \sqrt{2}d_i^{(u)'}}{A^3} \left(\text{arctg Atg } \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
& + \frac{\sin \sqrt{2}(d_{jp}^{(r)'} + d_i^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{jp}^{(r)'} \sin \sqrt{2}d_i^{(u)'}}{A} \left(\text{arctg Atg } \sqrt{2}\varphi \right. \\
& \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right)] z_{jp}^{(r)} u_i^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{jp}^{(r)'}) \sin \sqrt{2}(c' + d_i^{(u)'})} e_r (A_{ij}^{tp})' e'_s e_u Q_{ip}^{(s)} \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_j^{(r)'}}{A^3} \left(\text{arctg Atg } \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
& + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_j^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_j^{(r)'}}{A} \left(\text{arctg Atg } \sqrt{2}\varphi \right. \\
& \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right)] z_{ip}^{(s)} u_j^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_j^{(r)'})} e_r (Q_{ij}^{(t)})' Q_{ip}^{(s)},
\end{aligned}$$

$$a_{11} = u_p - g_{11}(c').$$

第二章 记号及预备知识

首先给出正规 Siegel 的定义.

给定非负整数 n_{ij} , $1 \leq i \leq j \leq N$, 其中 $n_{ii} = 1$, $1 \leq i \leq N$. 记 $n = \sum_{1 \leq i \leq j \leq N} n_{ij}$.

\mathbb{C}^n 中点 z 的坐标排为

$$z = (s_1, z_2, s_2, \dots, z_N, s_N), \quad z_j = (z_{1j}, z_{2j}, \dots, z_{j-1,j}),$$

其中

$$s_i \in \mathbb{C}, \quad z_{ij} \in \mathbb{C}^{n_{ij}}, \quad z_{ij} = (z_{ij}^{(1)}, \dots, z_{ij}^{(n_{ij})}).$$

当 z 的坐标中 $s_j = 1$, 其余坐标全为零时, 记 z 为 e_{jj} ; 当 z 的坐标中 $z_{ij}^{(t)} = 1$, 其余坐标全为零时, 记 z 为 $e_{ij}^{(t)}$;

给定非负整数 m_i , $1 \leq i \leq N$, 记 $m = \sum_{i=1}^N m_i$. \mathbb{C}^m 中点 u 的坐标排为

$$u = (u_1, \dots, u_N),$$

其中

$$u_j \in \mathbb{C}^{m_j}, \quad u_j = (u_j^{(1)}, \dots, u_j^{(m_j)}), \quad 1 \leq j \leq N$$

当 u 的坐标中 $u_j^{(t)} = 1$, 其余坐标全为零时, 记 u 为 $e_j^{(t)}$;

记 $e_i = (0, \dots, 1, \dots, 0)$, 其中 1 为第 i 个分量, $n \times m$ 阶矩阵 A 的第 i 行第 j 列元素可记为 $e_i A e_j'$, 记 E_{sr} 为第 s 行, r 列元素为 1, 其余元素为 0 的矩阵.

定义 2.1 设 A_{ij}^{tk} , $t = 1, \dots, n_{ij}$ 为 $n_{ik} \times n_{jk}$ 阶实矩阵, $1 \leq i < j \leq N$; $Q_{ij}^{(t)}$, $t = 1, \dots, n_{ij}$ 为 $m_i \times m_j$ 阶复矩阵, $1 \leq i < j \leq N$. 矩阵组 $\{A_{ij}^{tk}, Q_{ij}^{(t)}, 1 \leq t \leq n_{ij}, 1 \leq i < j < k \leq N\}$ 称为 N 矩阵组. 如果它们适合以下 8 个条件

(1) $n_{ik} = 0$ 蕴含 $n_{ij}n_{jk} = 0$, $j = i+1, \dots, k-1$;

(2)

$$(A_{ij}^{sk})' A_{ij}^{tk} + (A_{ij}^{tk})' A_{ij}^{sk} = 2\delta_{s,t} I^{(n_{jk})},$$

其中 $1 \leq s, t \leq n_{ij}$, $1 \leq i < j < k \leq N$;

(3)

$$A_{ij}^{sk} A_{jp}^{tk} = \sum_r (e_r A_{ij}^{sp} e_r') A_{ip}^{rk},$$

其中 $1 \leq s \leq n_{ij}$, $1 \leq t \leq n_{jp}$, $1 \leq i < j < p < k \leq N$;

(4)

$$(A_{ij}^{sk})' A_{ip}^{tk} = \sum_r (e_t A_{ij}^{sp} e_r') A_{jp}^{rk},$$

其中 $1 \leq s \leq n_{ij}$, $1 \leq t \leq n_{ip}$, $1 \leq i < j < p < k \leq N$;

(5) $m_k = 0$ 蕴含 $n_{ij}m_j = 0$, $j = i+1, \dots, N$;

(6)

$$\overline{(Q_{ij}^{(s)})'} Q_{ij}^{(t)} + \overline{(Q_{ij}^{(t)})'} Q_{ij}^{(s)} = 2\delta_{s,t} I^{(m_j)},$$

其中 $1 \leq s, t \leq n_{ij}, 1 \leq i < j \leq N$;

(7)

$$Q_{ij}^{(s)} Q_{jk}^{(t)} = \sum_r (e_r A_{ij}^{sk} e_r') Q_{ik}^{(r)},$$

其中 $1 \leq s \leq n_{ij}, 1 \leq t \leq n_{jk}, 1 \leq i < j < k \leq N$;

(8)

$$\overline{(Q_{ij}^{(s)})'} Q_{ik}^{(t)} = \sum_r (e_t A_{ij}^{sk} e_r') Q_{jk}^{(r)},$$

其中 $1 \leq s \leq n_{ij}, 1 \leq t \leq n_{ik}, 1 \leq i < j < k \leq N$.记 $x \in \mathbb{R}^n$, 其中

$$n = \sum_{1 \leq i < j \leq N} n_{ij},$$

又 $n_{11} = \cdots = n_{NN} = 1$. 任取 $x \in \mathbb{R}^n$, 则 x 可记作

$$x = (r_1, x_2, r_2, \cdots, x_N, r_N), \quad x_j = (x_{1j}, \cdots, x_{j-1,j}),$$

其中 $r_1, \cdots, r_N \in \mathbb{R}, x_{ij} \in \mathbb{R}^{n_{ij}}$. 记

$$C_j(x) = \begin{pmatrix} r_j & x_{j,j+1} & \cdots & x_{jN} \\ x'_{j,j+1} & r_{j+1} I^{(n_{j,j+1})} & \cdots & R_{j+1,N}^{(j)}(x) \\ \vdots & & & \vdots \\ x'_{jN} & R_{j+1,N}^{(j)}(x)' & \cdots & r_N I^{(n_{jN})} \end{pmatrix} \quad (2.1)$$

其中 $1 \leq j \leq N$, 于是 $C_j(x)$ 为

$$n'_j = n_{jj} + n_{j,j+1} + \cdots + n_{jN}$$

阶实对称方阵, 其中 $n_{jk} \times n_{jl}$ 阶矩阵

$$R_{kl}^{(j)}(x) = \sum_r e_r' x_{kl} (A_{jk}^r)'', \quad 1 \leq j < k < l \leq N \quad (2.2)$$

记 $u \in \mathbb{C}^m, m = m_1 + \cdots + m_N, u = (u_1, \cdots, u_N), u_j \in \mathbb{C}^{m_j}$, 则

$$R_j(u) = \begin{pmatrix} u_j \\ R_{j+1}^{(j)}(u) \\ \vdots \\ R_N^{(j)}(u) \end{pmatrix} \quad (2.3)$$

为 $n'_j \times m_j$ 阶矩阵, 其中

$$R_k^{(j)}(u) = \sum_r e'_r u_k \overline{Q_{jk}^{(r)'}}', \quad 1 \leq j < k \leq N \quad (2.4)$$

定义 2.2 给定 N 矩阵组 $B = \{ A_{ij}^{tk}, Q_{ij}^{(t)} \}$, 由 N 矩阵组 B 定义的秩为 N 的正规 Siegel 域定义为

$$\{ (z, u) \in \mathbb{C}^n \times \mathbb{C}^m \mid \text{Im} C_j(z) - \text{Re} R_j(u) \overline{R_j(u)'} > 0, \quad 1 \leq j \leq N \},$$

记作 $D(v_N, F)$.

定义 2.3 给定 $1 \leq i < j \leq N$, 并设 $n_{ij} > 0$, 称 $N \times N$ 对称方阵

$$S = \begin{pmatrix} n_{11} & \cdots & n_{1N} \\ \vdots & & \vdots \\ n_{N1} & \cdots & n_{NN} \end{pmatrix}$$

关于指标 (i, j) 适合 $Z(i, j)$ 条件, 如果

(i) 任取 $l \in \{i+1, \dots, j-1\}$, 只要 $(n_{il}, n_{lj}) \neq 0$, 就有

$$\begin{aligned} n_{il} &= n_{lj} = n_{ij}, \\ n_{pi} &= n_{pl} = n_{pj}, \quad p < i, \\ n_{ip} &= n_{lp} = n_{jp}, \quad j < p; \end{aligned}$$

(ii) 当 $p \in \{i+1, \dots, j-1\}$ 时有

$$n_{ip} = n_{pl} = n_{pj}, \quad i < p < l; \quad n_{ip} = n_{lp} = n_{jp}, \quad l < p < j.$$

引理 2.4 [16] 设 $n_{ij} > 0$, 且矩阵 S 关于指标 (i, j) 适合定义 2.3 中的条件, 则有

$$\begin{aligned} \sum_t (A_{pi}^{tj})' (e'_u e_v + e'_v e_u) A_{pi}^{tj} &= 2\delta_{uv} I^{(n_{ij})}, \\ \sum_t A_{pi}^{tj} (e'_u e_v + e'_v e_u) (A_{pi}^{tj})' &= 2\delta_{uv} I^{(n_{pj})}, \quad p < i, \\ \sum_t (A_{ip}^{tj})' (e'_u e_v + e'_v e_u) A_{ip}^{tj} &= 2\delta_{uv} I^{(n_{pj})}, \\ \sum_t A_{ip}^{tj} (e'_u e_v + e'_v e_u) (A_{ip}^{tj})' &= 2\delta_{uv} I^{(n_{ij})}, \quad i < p < j, \end{aligned}$$

以及

$$\begin{aligned} A_{ij}^{tl} (A_{ij}^{sl})' + A_{ij}^{sl} (A_{ij}^{tl})' &= 2\delta_{st} I^{(n_{ij})}, \\ A_{kl}^{sj} (A_{il}^{tj})' &= \sum_r (e_s A_{ki}^{rl} e'_t) A_{kl}^{rj}, \quad k < i < l < j, \\ A_{kj}^{sp} (A_{ij}^{tp})' &= \sum_r (e_s A_{ki}^{rj} e'_t) A_{kj}^{rp}, \quad k < i < j < p, \end{aligned}$$

$$Q_{kl}^{(s)} \overline{(Q_{il}^{(t)})'} = \sum_r (e_s A_{ki}^{rl} e_t') Q_{ki}^{(r)}, \quad k < i < l < j,$$

$$Q_{kj}^{(s)} \overline{(Q_{ij}^{(t)})'} = \sum_r (e_s A_{ki}^{rj} e_t') Q_{ki}^{(r)}, \quad k < i < j < p.$$

引理 2.5 [17] \mathbb{R}^n 或 \mathbb{C}^n 中的域 D 上的解析 (或全纯) 向量场 $X = \sum_{i=1}^n \xi(x) \frac{\partial}{\partial x_i} \in \text{aut}(D)$ 决定的单参数子群 $\exp(tX)$ 为域 D 上的解析 (或全纯) 自同构 $y = f(x, t), \forall t \in \mathbb{R}^n$, 它是常微分方程组

$$\frac{dy(t)}{dt} = \xi(y(t))$$

的适合初值

$$y(0) = x$$

的唯一解析解, 其中 $\xi(x) = (\xi_1(x), \dots, \xi_n(x))$.

定义 2.6 指标 $1 \leq i_1 < \dots < i_p \leq N$ 是适合下面条件的最大集, 这些条件是

(1) 实对称方阵 S 关于指标 (i_σ, i_τ) 适合定义 2.3 中的条件, 并且有

$$m_{i_\sigma} = m_{i_\mu} = m_{i_\tau}, \quad i_\sigma < i_\mu < i_\tau;$$

(2) 当 $i \neq i_1 \dots i_{\sigma-1}, i < i_\sigma$ 时, 实对称方阵 S 关于指标 (i, i_σ) 不适合定义 2.3 中的条件;

(3)

$$n_{i_\sigma i} = 0, \quad i_\sigma < i, \quad i \neq i_{\sigma+1}, \dots, i_p;$$

(4)

$$\sum_r (Q_{ii_\sigma}^{(r)})' (e_u' e_v + e_v' e_u) Q_{ii_\sigma}^{(r)} = 0, \quad 1 \leq u, v \leq m_i, \quad 1 \leq i \leq i_\sigma.$$

引理 2.7 [16] $\text{Iso}(D(v_N, F))$ 是一固定点 $p = (\sqrt{-1}v_0, 0) \in D(v_N, F)$ 的迷向子群, $\text{iso}_p(D(v_N, F))$ 为 $\text{Iso}_p(D(v_N, F))$ 的李代数, 则 $\text{iso}_p(D(v_N, F))$ 有空间直接和分解

$$\text{iso}_p(D(v_N, F)) = o(D(v_N, F)) + \tilde{y}(D(v_N, F)) + \tilde{L}_1 + \tilde{L}_2$$

其中

(i)

$$o(D(v_N, F)) = \left\{ \sum_{i < j} z_{ij} L_{ij} \frac{\partial'}{\partial z_{ij}} + \sum_i u_i K_i \frac{\partial'}{\partial u_i} \right\}$$

是一个子代数, L_{ij} 是一个 $n_{ij} \times n_{ij}$ 阶实反对称矩阵满足

$$L_{ik}' A_{ij}^{tk} + A_{ij}^{tk} L_{jk} = \sum_r (e_r L_{ij} e_t') A_{ij}^{rk},$$

K_i 是一个 $m_i \times m_i$ 阶反 Hermitian 矩阵满足

$$\overline{K_i}' Q_{ij}^{(l)} + Q_{ij}^{(l)} K_j = \sum_r (e_r L_{ij} e_t') Q_{ij}^{(r)},$$

(ii) $\tilde{y}(D(v_N, F))$ 是一个子空间, 有基

$$X_{ij}^{(t)} - Z_{ij}^{(t)}, \quad 1 \leq t \leq n_{ij}, \quad X_{ij}^{(t)}, \quad Z_{ij}^{(t)} \in L_0,$$

(iii) \tilde{L}_1 是一个子空间, 有基

$$Y_{i\sigma}^{(t)} - \tilde{P}_{i\sigma}^{(t)}, \quad \tilde{Y}_{i\sigma}^{(t)} + P_{i\sigma}^{(t)}, \quad 1 \leq t \leq m_{i\sigma}, \quad 1 \leq \sigma \leq \rho,$$

$i_{\sigma_1}, \dots, i_{\sigma_\rho}$ 满足定义 2.6.

(iv) \tilde{L}_2 是一个子空间, 有基

$$B_{i\sigma} + \frac{\partial}{\partial s_{i\sigma}}, \quad T_{i\sigma i\tau}^{(t)} + 2 \frac{\partial}{\partial z_{i\sigma i\tau}^{(t)}}, \quad 1 \leq t \leq n_{i\sigma i\tau}, \quad 1 \leq \sigma < \tau \leq \rho,$$

$i_{\sigma_1}, \dots, i_{\sigma_\rho}$ 满足定义 2.6.

其中

$$\begin{aligned} X_{ij}^{(t)} - Z_{ij}^{(t)} &= 2z_{ij}^{(t)} \frac{\partial}{\partial s_i} - 2z_{ij}^{(t)} \frac{\partial}{\partial s_j} + (s_j - s_i) \frac{\partial}{\partial z_{ij}^{(t)}} + \sum_{p < i} \sum_s z_{pj} A_{pi}^{sj} e_t' \frac{\partial}{\partial z_{pi}^{(s)}} \\ &\quad - \sum_{p < i} \sum_s z_{pi}^{(s)} e_t (A_{pi}^{sj})' \frac{\partial}{\partial z_{pj}} + \sum_{i < p < j} \sum_s e_t A_{ip}^{sj} z_{pj}' \frac{\partial}{\partial z_{ip}^{(s)}} - \sum_{i < p < j} \sum_s z_{ip}^{(s)} e_t A_{ip}^{sj} \frac{\partial}{\partial z_{pj}} \\ &\quad + \sum_{p > j} z_{jp} (A_{ij}^{tp})' \frac{\partial}{\partial z_{ip}} - \sum_{p > j} z_{ip} A_{ij}^{tp} \frac{\partial}{\partial z_{jp}} + u_j \overline{(Q_{ij}^{(t)})}' \frac{\partial}{\partial u_i} - u_i Q_{ij}^{(t)} \frac{\partial}{\partial u_j}; \end{aligned}$$

$$\begin{aligned} Y_i^{(t)} - \tilde{P}_i^{(t)} &= 2(\sqrt{-1}u_i^{(t)} s_i - u_i^{(t)}) \frac{\partial}{\partial s_i} + 2\sqrt{-1} \sum_{p < i} \sum_s z_{pi}^{(s)} u_p Q_{pi}^{(s)} e_t' \frac{\partial}{\partial s_p} \\ &\quad + 2\sqrt{-1} \sum_{i < p} \sum_s z_{ip}^{(s)} u_p \overline{(Q_{ip}^{(s)})}' e_t' \frac{\partial}{\partial s_p} + \sqrt{-1} \sum_{p < i} \sum_s u_p Q_{pi}^{(s)} e_t' [s_i \frac{\partial}{\partial z_{pi}^{(s)}} + \sqrt{-1} \frac{\partial}{\partial z_{pi}^{(s)}}] \\ &\quad + \sum_{l < p} \sum_u z_{li} A_{lp}^{ui} e_s' \frac{\partial}{\partial z_{lp}^{(u)}} + \sum_{p < l < i} \sum_u e_s A_{pl}^{ui} z_{li}' \frac{\partial}{\partial z_{pl}^{(u)}} + \sum_{i < l} z_{il} (A_{pi}^{sl})' \frac{\partial}{\partial z_{pl}^{(s)}} \\ &\quad + \sqrt{-1} \sum_{p < i} \sum_{s, r} z_{pi}^{(s)} u_i \overline{(Q_{pi}^{(r)})}' Q_{pi}^{(s)} e_t' \frac{\partial}{\partial z_{pi}^{(r)}} + \sqrt{-1} \sum_{i < p} \sum_{s, r} z_{ip}^{(s)} u_i Q_{ip}^{(r)} \overline{(Q_{ip}^{(s)})}' e_t' \frac{\partial}{\partial z_{ip}^{(r)}} \\ &\quad + \sqrt{-1} \sum_{i < p} \sum_s u_p \overline{(Q_{ip}^{(s)})}' e_t' [s_i \frac{\partial}{\partial z_{ip}^{(s)}} + \sqrt{-1} \frac{\partial}{\partial z_{ip}^{(s)}}] + \sum_{l < i} \sum_u z_{li}^{(u)} e_s (A_{li}^{up})' \frac{\partial}{\partial z_{lp}^{(u)}} \\ &\quad + \sum_{i < l < p} \sum_u z_{il}^{(u)} e_s A_{il}^{up} \frac{\partial}{\partial z_{lp}^{(u)}} + \sum_{p < l} z_{il} A_{ip}^{sl} \frac{\partial}{\partial z_{pl}^{(s)}} + \sum_{p < i} \sum_s z_{pi}^{(s)} e_t \overline{(Q_{pi}^{(s)})}' \frac{\partial}{\partial u_p} \end{aligned}$$

$$\begin{aligned}
& + \sqrt{-1} \sum_{p < i} \sum_s u_p Q_{pi}^{(s)} e'_t u_i (Q_{pi}^{(s)})' \frac{\partial'}{\partial u_p} + (2\sqrt{-1} u_i^{(t)} u_i + s_i e_t - \sqrt{-1} e_t) \frac{\partial'}{\partial u_i} \\
& + \sum_{i < p} \sum_s z_{ip}^{(s)} e_t Q_{ip}^{(s)} \frac{\partial'}{\partial u_p} + \sqrt{-1} \sum_{i < p} \sum_s u_p (Q_{ip}^{(s)})' e'_t u_i Q_{ip}^{(s)} \frac{\partial'}{\partial u_p}, \quad i \in \{i_1, \dots, i_p\}, \\
\bar{Y}_i^{(t)} + P_i^{(t)} & = 2(u_i^{(t)} s_i + \sqrt{-1} u_i^{(t)}) \frac{\partial}{\partial s_i} + 2 \sum_{p < i} \sum_s z_{pi}^{(s)} u_p Q_{pi}^{(s)} e'_t \frac{\partial}{\partial s_p} \\
& + 2 \sum_{i < p} \sum_s z_{ip}^{(s)} u_p (Q_{ip}^{(s)})' e'_t \frac{\partial}{\partial s_p} + \sum_{p < i} \sum_s u_p Q_{pi}^{(s)} e'_t [s_i \frac{\partial}{\partial z_{pi}^{(s)}} + \sqrt{-1} \frac{\partial}{\partial z_{pi}^{(s)}}] \\
& + \sum_{l < p} \sum_u z_{li} A_{lp}^{ui} e'_s \frac{\partial}{\partial z_{lp}^{(u)}} + \sum_{p < l < i} \sum_u e_s A_{pl}^{ui} z'_{li} \frac{\partial}{\partial z_{pl}^{(u)}} + \sum_{i < l} z_{il} (A_{pi}^{sl})' \frac{\partial'}{\partial z_{pl}'} \\
& + \sum_{p < i} \sum_{s,r} z_{pi}^{(s)} u_i (Q_{pi}^{(r)})' Q_{pi}^{(s)} e'_t \frac{\partial}{\partial z_{pi}^{(r)}} + \sum_{i < p} \sum_{s,r} z_{ip}^{(s)} u_i Q_{ip}^{(r)} (Q_{ip}^{(s)})' e'_t \frac{\partial}{\partial z_{ip}^{(r)}} \\
& + \sum_{i < p} \sum_s u_p (Q_{ip}^{(s)})' e'_t [s_i \frac{\partial}{\partial z_{ip}^{(s)}} + \sqrt{-1} \frac{\partial}{\partial z_{ip}^{(s)}}] + \sum_{l < i} \sum_u z_{li}^{(u)} e_s (A_{li}^{up})' \frac{\partial'}{\partial z_{lp}'} \\
& + \sum_{i < l < p} \sum_u z_{il}^{(u)} e_s A_{il}^{up} \frac{\partial'}{\partial z_{lp}'} + \sum_{p < l} z_{il} A_{ip}^{sl} \frac{\partial'}{\partial z_{pl}'} \\
& + \sqrt{-1} \sum_{p < i} \sum_s z_{pi}^{(s)} e_t (Q_{pi}^{(s)})' \frac{\partial'}{\partial u_p} + \sum_{p < i} \sum_s u_p Q_{pi}^{(s)} e'_t u_i (Q_{pi}^{(s)})' \frac{\partial'}{\partial u_p} \\
& + (2u_i^{(t)} u_i + \sqrt{-1} s_i e_t + e_t) \frac{\partial'}{\partial u_i} + \sqrt{-1} \sum_{i < p} \sum_s z_{ip}^{(s)} e_t Q_{ip}^{(s)} \frac{\partial'}{\partial u_p} \\
& + \sum_{i < p} \sum_s u_p (Q_{ip}^{(s)})' e'_t u_i Q_{ip}^{(s)} \frac{\partial'}{\partial u_p}, \quad i \in \{i_1, \dots, i_p\}; \\
B_i + \frac{\partial}{\partial s_i} & = \sum_{p < i} z_{pi} z'_{pi} \frac{\partial}{\partial s_p} + \sum_{p > i} z_{ip} z'_{ip} \frac{\partial}{\partial s_p} + s_i^2 \frac{\partial}{\partial s_i} + s_i \sum_{p < i} z_{pi} \frac{\partial'}{\partial z_{pi}'} + s_i \sum_{p > i} z_{ip} \frac{\partial'}{\partial z_{ip}'} \\
& + \sum_{k < p < i} \sum_s z_{ki} A_{kp}^{si} z'_{pi} \frac{\partial}{\partial z_{kp}^{(s)}} + \sum_{k < i < p} \sum_s z_{ki}^{(s)} z_{ip} (A_{ki}^{sp})' \frac{\partial'}{\partial z_{kp}'} \\
& + \sum_{i < k < p} \sum_s z_{ik}^{(s)} z_{ip} A_{ik}^{sp} \frac{\partial'}{\partial z_{kp}'} + s_i u_i \frac{\partial'}{\partial u_i} + \sum_{p < i} \sum_s z_{pi}^{(s)} u_i (Q_{pi}^{(s)})' \frac{\partial'}{\partial u_p} \\
& + \sum_{p > i} \sum_s z_{ip}^{(s)} u_i Q_{ip}^{(s)} \frac{\partial'}{\partial u_p} + \frac{\partial}{\partial s_i}, \quad i \in \{i_1, \dots, i_p\},
\end{aligned}$$

$$\begin{aligned}
T_{ij}^{(t)} + 2 \frac{\partial}{\partial z_{ij}^{(t)}} &= 2s_i z_{ij}^{(t)} \frac{\partial}{\partial s_i} + 2s_j z_{ij}^{(t)} \frac{\partial}{\partial s_j} + 2 \sum_{p < i} \sum_s z_{pi}^{(s)} z_{pj} A_{pi}^{sj} e'_t \frac{\partial}{\partial s_p} \\
&+ 2 \sum_{i < p < j} \sum_s z_{ip}^{(s)} e_t A_{ip}^{sj} z'_{pj} \frac{\partial}{\partial s_p} + 2 \sum_{p > j} z_{ip} A_{ij}^{tp} z'_{jp} \frac{\partial}{\partial s_p} \\
&+ \sum_{p < i} [2z_{ij}^{(t)} z_{pi} + s_i \sum_s z_{pj} A_{pi}^{sj} e'_t e_s - \sum_{s,r} z_{pi}^{(s)} z_{ij} (A_{pi}^{sj})' A_{pi}^{rj} e'_t e_r] \frac{\partial'}{\partial z_{pi}} \\
&+ \sum_{i < p} [2z_{ij}^{(t)} z_{ip} + s_i \sum_{p < j} \sum_s e_t A_{ip}^{sj} z'_{pj} e_s - \sum_{p < j} \sum_{s,r} z_{ip}^{(s)} z_{ij} A_{ip}^{sj} (A_{ip}^{rj})' e'_t e_r \\
&+ s_i \sum_{p > j} z_{jp} (A_{ij}^{tp})' - \sum_{p > j} \sum_s z_{ij}^{(s)} z_{ip} A_{ij}^{sp} (A_{ij}^{tp})'] \frac{\partial'}{\partial z_{ip}} + \sum_{p > j} [s_j z_{ip} A_{ij}^{tp} \frac{\partial'}{\partial z_{jp}} \\
&+ \sum_{i < k < p} \sum_s z_{ik}^{(s)} z_{jp} (A_{ij}^{tp})' A_{ik}^{sp} \frac{\partial'}{\partial z_{kp}}] + (s_i s_j - z_{ij} z'_{ij}) \frac{\partial}{\partial z_{ij}^{(t)}} \\
&+ \sum_{p < k < i} \sum_{s,r} z_{pj} A_{pi}^{sj} e'_t e_s A_{pk}^{ri} z'_{ki} \frac{\partial}{\partial z_{pk}^{(r)}} + \sum_{k < p < i} \sum_{s,r} z_{pj} A_{pi}^{sj} e'_t e_s (A_{kp}^{ri})' z'_{ki} \frac{\partial}{\partial z_{kp}^{(r)}} \\
&+ \sum_{p < i < k} \sum_s z_{pj} A_{pi}^{sj} e'_t z_{ik} (A_{pi}^{sk})' \frac{\partial'}{\partial z_{pk}} + \sum_{k < i < p < j} \sum_{s,r} z_{ki}^{(r)} e_t A_{ip}^{sj} z'_{pj} e_s (A_{ki}^{rp})' \frac{\partial'}{\partial z_{kp}} \\
&+ s_j \sum_{k < i} \sum_s z_{ki}^{(s)} e_t (A_{ki}^{sj})' \frac{\partial'}{\partial z_{kj}} + \sum_{k < i < j < p} \sum_s z_{ki}^{(s)} z_{jp} (A_{ij}^{tp})' (A_{ki}^{sp})' \frac{\partial'}{\partial z_{kp}} \\
&+ \sum_{i < p < k, p < j} \sum_s e_t A_{ip}^{sj} z'_{pj} z_{ik} A_{ip}^{sk} \frac{\partial'}{\partial z_{pk}} + s_j \sum_{i < k < j} \sum_s z_{ik}^{(s)} e_t A_{ik}^{sj} \frac{\partial'}{\partial z_{kj}} \\
&+ \sum_{i < k < p < j} \sum_{s,r} e_t A_{ip}^{sj} z'_{pj} z_{ik}^{(r)} e_s A_{ik}^{rp} \frac{\partial'}{\partial z_{kp}} + \sum_{j < p < k} \sum_s z_{jp} (A_{ij}^{tp})' e'_s z_{ik} A_{ip}^{sk} \frac{\partial'}{\partial z_{pk}} \\
&+ s_j u_i Q_{ij}^{(t)} \frac{\partial'}{\partial u_j} + \sum_{p < i} \sum_s z_{pj} A_{pi}^{sj} e'_t u_i \overline{(Q_{pi}^{(s)})'} \frac{\partial'}{\partial u_p} + \sum_{i < p < j} \sum_s e_t A_{ip}^{sj} z'_{pj} u_i Q_{ip}^{(s)} \frac{\partial'}{\partial u_p} \\
&+ \sum_{p > j} \sum_s z_{jp} (A_{ij}^{tp})' e'_s u_i Q_{ip}^{(s)} \frac{\partial'}{\partial u_p} + \sum_{i < p} \sum_s z_{ip}^{(s)} u_j \overline{(Q_{ij}^{(t)})'} Q_{ip}^{(s)} \frac{\partial'}{\partial u_p} \\
&+ \sum_{p < i} \sum_s z_{pi}^{(s)} u_j \overline{(Q_{ij}^{(t)})'} \overline{(Q_{pi}^{(s)})'} \frac{\partial'}{\partial u_p} + (2z_{ij}^{(t)} u_i - \sum_s z_{ij}^{(s)} u_i Q_{ij}^{(s)} \overline{(Q_{ij}^{(t)})'}) \\
&+ \overline{(Q_{ij}^{(t)})'} s_i \frac{\partial'}{\partial u_i} + 2 \frac{\partial}{\partial z_{ij}^{(t)}}, \quad 1 \leq t \leq n_{ij}, \quad i < j, \quad i, j \in \{i_1, \dots, i_\rho\}.
\end{aligned}$$

第三章 正规 Siegel 域的迷向子群

本章第一节为许以超教授已做工作：给出了紧李子群 $\exp(o(D(v_N, F)))$ ，后三节我们通过求解一些常微分方程组，求出 $\tilde{y}(D(v_N, F))$, \tilde{L}_1 , \tilde{L}_2 中基元所决定的单参数子群，进而给出正规 Siegel 域一固定点 $(\sqrt{-1}v_0, 0)$ 的迷向子群的生成元集，即证明了第一章中的定理。

不妨设向量 $z = (s_1, z_2, s_2, \dots, z_N, s_N)$ 经全纯自同构 σ 作用后变为向量 $w = (r_1, w_2, r_2, \dots, w_N, r_N)$ ，向量 $u = (u_1, \dots, u_N)$ 变为向量 $v = (v_1, \dots, v_N)$ 。

§3.1 $\exp(o(D(v_N, F)))$

$\exp(o(D(v_N, F)))$ 可以表示为：

$$\begin{aligned} r_j &= s_j, \quad 1 \leq j \leq N, \\ w_{ij} &= z_{ij} O_{ij}, \quad 1 \leq i < j \leq N, \\ v_i &= u_i U_i, \quad 1 \leq i \leq N, \end{aligned}$$

其中 $O_{ij} \in O(n_{ij})$, $U_i \in U(m_i)$ ，且满足

$$O'_{ik} A_{ij}^{tk} O_{jk} = \sum_{r=1}^{n_{ij}} (e_r O_{ij} e'_t) A_{ij}^{rk}, \quad \bar{U}_i' Q_{ij}^{(t)} U_j = \sum_{r=1}^{n_{ij}} (e_r O_{ij} e'_t) Q_{ij}^{(r)}.$$

§3.2 $\exp(\theta(X_{ij}^{(t)} - Z_{ij}^{(t)}))$

在这一节，我们计算 $X_{ij}^{(t)} - Z_{ij}^{(t)}$ 所决定的单参数子群。由引理 2.5 列出满足零点初值为 (z, u) 的微分方程组

$$\begin{aligned} \frac{dr_i}{d\theta} &= 2w_{ij}^{(t)}, \\ \frac{dr_j}{d\theta} &= -2w_{ij}^{(t)}, \\ \frac{dw_{ij}^{(t)}}{d\theta} &= r_j - r_i, \\ \frac{dw_{pi}^{(s)}}{d\theta} &= w_{pj} A_{pi}^{sj} e'_t, \quad p < i, \\ \frac{dw_{pj}^{(s)}}{d\theta} &= -\sum_s w_{pi}^{(s)} e_t (A_{pi}^{sj})', \quad p < i, \\ \frac{dw_{ip}^{(s)}}{d\theta} &= e_t A_{ip}^{sj} w'_{pj}, \quad i < p < j, \\ \frac{dw_{pj}^{(s)}}{d\theta} &= -\sum_s w_{ip}^{(s)} e_t A_{ip}^{sj}, \quad i < p < j, \\ \frac{dw_{ip}}{d\theta} &= w_{jp} (A_{ij}^{tp})', \quad p > j, \\ \frac{dw_{jp}}{d\theta} &= -w_{ip} A_{ij}^{tp}, \quad p > j, \end{aligned}$$

$$\begin{aligned}\frac{dv_i}{d\theta} &= \overline{v_j(Q_{ij}^{(t)})'}, \\ \frac{dv_j}{d\theta} &= -v_i Q_{ij}^{(t)}, \\ \frac{dv_p}{d\theta} &= 0, \quad p \neq i, j.\end{aligned}$$

下面求解这个常微分方程组.

(1) 由 $\begin{cases} \frac{dv_p}{d\theta} = 0, \quad p \neq i, j \\ v_p(0) = u_p \end{cases}$, 可得 $v_p = u_p$.

(2) 由 $\begin{cases} \frac{dv_i}{d\theta} = \overline{v_j(Q_{ij}^{(t)})'} \\ \frac{dv_j}{d\theta} = -v_i Q_{ij}^{(t)} \end{cases}$ 可得 $\frac{d}{d\theta} \begin{pmatrix} v_i' \\ v_j' \end{pmatrix} = \begin{pmatrix} 0 & \overline{Q_{ij}^{(t)'}} \\ -Q_{ij}^{(t)'} & 0 \end{pmatrix} \begin{pmatrix} v_i' \\ v_j' \end{pmatrix}$,

该常系数齐线性方程组满足初值条件 $v_i(0) = u_i, v_j(0) = u_j$ 的解为

$$(v_i, v_j) = (u_i, u_j) \exp \theta \begin{pmatrix} 0 & -\overline{Q_{ij}^{(t)'}} \\ \overline{Q_{ij}^{(t)'}} & 0 \end{pmatrix}.$$

令

$$A = \begin{pmatrix} 0 & -\overline{Q_{ij}^{(t)'}} \\ \overline{Q_{ij}^{(t)'}} & 0 \end{pmatrix},$$

则

$$\begin{aligned}A^2 &= \begin{pmatrix} -\overline{Q_{ij}^{(t)'}} \overline{Q_{ij}^{(t)'}} & 0 \\ 0 & -\overline{Q_{ij}^{(t)'}} Q_{ij}^{(t)} \end{pmatrix} = \begin{pmatrix} -E & 0 \\ 0 & -E \end{pmatrix}, \\ A^{2n} &= (-1)^n \begin{pmatrix} E & 0 \\ 0 & E \end{pmatrix}, \quad A^{2n+1} = (-1)^n \begin{pmatrix} 0 & -\overline{Q_{ij}^{(t)'}} \\ \overline{Q_{ij}^{(t)'}} & 0 \end{pmatrix},\end{aligned}$$

记

$$\exp \theta A = \begin{pmatrix} A_{11}(\theta) & A_{12}(\theta) \\ A_{21}(\theta) & A_{22}(\theta) \end{pmatrix},$$

则

$$\begin{aligned}\begin{pmatrix} A_{11}(\theta) & 0 \\ 0 & A_{22}(\theta) \end{pmatrix} &= E + \sum_{n=1}^{\infty} \frac{(-1)^n \theta^{2n}}{(2n)!} \begin{pmatrix} E & 0 \\ 0 & E \end{pmatrix} = \sum_{n=0}^{\infty} \frac{(-1)^n \theta^{2n}}{(2n)!} E = \cos \theta E, \\ \begin{pmatrix} 0 & A_{12}(\theta) \\ A_{21}(\theta) & 0 \end{pmatrix} &= \sum_{n=0}^{\infty} \frac{(-1)^n \theta^{2n+1}}{(2n+1)!} \begin{pmatrix} 0 & -\overline{Q_{ij}^{(t)'}} \\ \overline{Q_{ij}^{(t)'}} & 0 \end{pmatrix} = \sin \theta \begin{pmatrix} 0 & -\overline{Q_{ij}^{(t)'}} \\ \overline{Q_{ij}^{(t)'}} & 0 \end{pmatrix},\end{aligned}$$

所以

$$(v_i, v_j) = (u_i, u_j) \exp \theta A = (u_i \cos \theta + u_j \overline{Q_{ij}^{(t)'}} \sin \theta, -u_i \overline{Q_{ij}^{(t)'}} \sin \theta + u_j \cos \theta).$$

即

$$\begin{aligned}v_i &= u_i \cos \theta + u_j \overline{Q_{ij}^{(t)}} \sin \theta, \\v_j &= -u_i Q_{ij}^{(t)} \sin \theta + u_j \cos \theta.\end{aligned}$$

(3)

$$\text{由 } \begin{cases} \frac{dr_i}{d\theta} = 2w_{ij}^{(t)} \\ \frac{dr_j}{d\theta} = -2w_{ij}^{(t)} \\ \frac{dw_{ij}^{(t)}}{d\theta} = r_j - r_i \end{cases} \text{ 可得 } \frac{d}{d\theta} \begin{pmatrix} r_i \\ r_j \\ w_{ij}^{(t)} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 2 \\ 0 & 0 & -2 \\ -1 & 1 & 0 \end{pmatrix} \begin{pmatrix} r_i \\ r_j \\ w_{ij}^{(t)} \end{pmatrix},$$

该常系数齐线性方程组满足初值条件 $r_i(0) = s_i, r_j(0) = s_j, w_{ij}^{(t)}(0) = z_{ij}^{(t)}$ 的解为

$$(r_i, r_j, w_{ij}^{(t)}) = (s_i, s_j, z_{ij}^{(t)}) \exp \theta \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 1 \\ 2 & -2 & 0 \end{pmatrix}.$$

令

$$A = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 1 \\ 2 & -2 & 0 \end{pmatrix},$$

则

$$A^2 = \begin{pmatrix} -2 & 2 & 0 \\ 2 & -2 & 0 \\ 0 & 0 & -4 \end{pmatrix} = 2 \begin{pmatrix} -1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & -2 \end{pmatrix},$$

因为:

$$\begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}^n = (-2)^{n-1} \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix},$$

所以:

$$A^{2n} = (-1)^n 2^{2n-1} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}, \quad A^{2n+1} = (-1)^n 2^{2n} \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 1 \\ 2 & -2 & 0 \end{pmatrix},$$

记

$$\exp \theta A = \begin{pmatrix} A_{11}(\theta) & A_{12}(\theta) & A_{13}(\theta) \\ A_{21}(\theta) & A_{22}(\theta) & A_{23}(\theta) \\ A_{31}(\theta) & A_{32}(\theta) & A_{33}(\theta) \end{pmatrix}.$$

则

$$\begin{pmatrix} 0 & 0 & A_{13}(\theta) \\ 0 & 0 & A_{23}(\theta) \\ A_{31}(\theta) & A_{32}(\theta) & 0 \end{pmatrix} = \sum_{n=0}^{\infty} \frac{(-1)^n 2^{2n} \theta^{2n+1}}{(2n+1)!} \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 1 \\ 2 & -2 & 0 \end{pmatrix} = \frac{\sin 2\theta}{2} \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 1 \\ 2 & -2 & 0 \end{pmatrix},$$

$$\begin{aligned}
\begin{pmatrix} A_{11}(\theta) & A_{12}(\theta) & 0 \\ A_{21}(\theta) & A_{22}(\theta) & 0 \\ 0 & 0 & A_{33}(\theta) \end{pmatrix} &= E + \sum_{n=1}^{\infty} \frac{(-1)^n 2^{2n-1} \theta^{2n}}{(2n)!} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \\
&= \frac{1}{2} \cos 2\theta \begin{pmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} + \begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 \end{pmatrix} \\
&= \begin{pmatrix} \frac{1}{2} \cos 2\theta + \frac{1}{2} & -\frac{1}{2} \cos 2\theta + \frac{1}{2} & 0 \\ -\frac{1}{2} \cos 2\theta + \frac{1}{2} & \frac{1}{2} \cos 2\theta + \frac{1}{2} & 0 \\ 0 & 0 & \cos 2\theta \end{pmatrix},
\end{aligned}$$

所以:

$$(r_i, r_j, w_{ij}^{(t)}) = (s_i, s_j, z_{ij}^{(t)}) \begin{pmatrix} \frac{1}{2} \cos 2\theta + \frac{1}{2} & -\frac{1}{2} \cos 2\theta + \frac{1}{2} & -\frac{1}{2} \sin 2\theta \\ -\frac{1}{2} \cos 2\theta + \frac{1}{2} & \frac{1}{2} \cos 2\theta + \frac{1}{2} & \frac{1}{2} \sin 2\theta \\ \sin 2\theta & -\sin 2\theta & \cos 2\theta \end{pmatrix},$$

即:

$$\begin{aligned}
r_i &= \left(\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_i + \left(-\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_j + \sin 2\theta z_{ij}^{(t)}, \\
r_j &= \left(-\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_i + \left(\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_j - \sin 2\theta z_{ij}^{(t)}, \\
w_{ij}^{(t)} &= -\frac{1}{2} \sin 2\theta s_i + \frac{1}{2} \sin 2\theta s_j + \cos 2\theta z_{ij}^{(t)}.
\end{aligned}$$

(4) $j < p$ 时, 同 (2) 的讨论.

满足初值条件 $w_{ip}(0) = z_{ip}$, $w_{jp}(0) = z_{jp}$ 的解为

$$\begin{aligned}
w_{ip} &= z_{ip} \cos \theta + z_{jp} (A_{ij}^{tp})' \sin \theta, \\
w_{jp} &= -z_{ip} A_{ij}^{tp} \sin \theta + z_{jp} \cos \theta.
\end{aligned}$$

(5) $p < i$ 时

由 $\begin{cases} \frac{dw_{pi}^{(s)}}{d\theta} = w_{pj} A_{pi}^{sj} e_t', & s = 1, \dots, n_{pi}, \\ \frac{dw_{pj}}{d\theta} = -\sum_s w_{pi}^{(s)} e_t (A_{pi}^{sj})' \end{cases}$ 可得

$$\frac{d}{d\theta} \begin{pmatrix} w_{pi}^{(1)} \\ \vdots \\ w_{pi}^{(n_{pi})} \\ w_{pj}' \end{pmatrix} = \begin{pmatrix} 0 & \cdots & 0 & e_t (A_{pi}^{1j})' \\ \vdots & & \vdots & \vdots \\ 0 & \cdots & 0 & e_t (A_{pi}^{n_{pi}j})' \\ -A_{pi}^{1j} e_t' & \cdots & -A_{pi}^{n_{pi}j} e_t' & 0 \end{pmatrix} \begin{pmatrix} w_{pi}^{(1)} \\ \vdots \\ w_{pi}^{(n_{pi})} \\ w_{pj}' \end{pmatrix},$$

该常系数齐线性方程组满足初值条件 $(w_{pi}, w_{pj})(0) = (z_{pi}, z_{pj})$ 的解为

$$(w_{pi}^{(1)}, \dots, w_{pi}^{(n_{pi})}, w_{pj}) = (z_{pi}^{(1)}, \dots, z_{pi}^{(n_{pi})}, z_{pj}) \exp \theta \begin{pmatrix} 0 & \dots & 0 & -e_t(A_{pi}^{1j})' \\ \vdots & & \vdots & \vdots \\ 0 & \dots & 0 & -e_t(A_{pi}^{n_{pi}j})' \\ A_{pi}^{1j} e_t' & \dots & A_{pi}^{n_{pi}j} e_t' & 0 \end{pmatrix}.$$

令

$$A = \begin{pmatrix} 0 & \dots & 0 & -e_t(A_{pi}^{1j})' \\ \vdots & & \vdots & \vdots \\ 0 & \dots & 0 & -e_t(A_{pi}^{n_{pi}j})' \\ A_{pi}^{1j} e_t' & \dots & A_{pi}^{n_{pi}j} e_t' & 0 \end{pmatrix}, \quad \beta = \begin{pmatrix} e_t(A_{pi}^{1j})' \\ \vdots \\ e_t(A_{pi}^{n_{pi}j})' \end{pmatrix} = \sum_{s=1}^{n_{pi}} e_s' e_t (A_{pi}^{sj})'.$$

则

$$A = \begin{pmatrix} 0 & -\beta \\ \beta' & 0 \end{pmatrix},$$

$$\beta\beta' = \sum_{s=1}^{n_{pi}} \sum_{r=1}^{n_{pi}} e_s' e_t (A_{pi}^{sj})' A_{pi}^{rj} e_t' e_r = E, \quad \beta'\beta = \sum_{s=1}^{n_{pi}} A_{pi}^{sj} E_{tt} (A_{pi}^{sj})' = E.$$

$$A^2 = \begin{pmatrix} -\beta\beta' & 0 \\ 0 & -\beta'\beta \end{pmatrix} = -E,$$

$$A^{2n} = (-1)^n E, \quad A^{2n+1} = (-1)^n \begin{pmatrix} 0 & -\beta \\ \beta' & 0 \end{pmatrix},$$

记

$$\exp \theta A = \begin{pmatrix} A_{11}(\theta) & A_{12}(\theta) \\ A_{21}(\theta) & A_{22}(\theta) \end{pmatrix},$$

则

$$\begin{pmatrix} A_{11}(\theta) & 0 \\ 0 & A_{22}(\theta) \end{pmatrix} = E + \sum_{n=1}^{\infty} \frac{(-1)^n \theta^{2n}}{(2n)!} E = \cos \theta E,$$

$$\begin{pmatrix} 0 & A_{12}(\theta) \\ A_{21}(\theta) & 0 \end{pmatrix} = \sum_{n=0}^{\infty} \frac{(-1)^n \theta^{2n+1}}{(2n+1)!} \begin{pmatrix} 0 & -\beta \\ \beta' & 0 \end{pmatrix} = \sin \theta \begin{pmatrix} 0 & -\beta \\ \beta' & 0 \end{pmatrix},$$

所以

$$(w_{pi}^{(1)}, \dots, w_{pi}^{(n_{pi})}, w_{pj}) = (z_{pi}^{(1)}, \dots, z_{pi}^{(n_{pi})}, z_{pj}) \begin{pmatrix} \cos \theta E & \sin \theta (-\beta) \\ \sin \theta \beta' & \cos \theta E \end{pmatrix}.$$

即

$$w_{pi} = z_{pi} \cos \theta + z_{pj} \sum_{s=1}^{n_{pi}} A_{pi}^{sj} e'_t e_s \sin \theta,$$

$$w_{pj} = -z_{pi} \sum_{s=1}^{n_{pi}} e'_s e_t (A_{pi}^{sj})' \sin \theta + z_{pj} \cos \theta.$$

(6) $i < p < j$ 时, 同 (5) 的讨论.

$$\begin{cases} \frac{dw_{ip}^{(s)}}{d\theta} = e_t A_{ip}^{sj} w_{pj}^{(s)}, & s = 1, \dots, n_{ip} \\ \frac{dw_{pj}^{(s)}}{d\theta} = -\sum_s w_{ip}^{(s)} e_t A_{ip}^{sj} \end{cases} \text{ 满足初值条件 } (w_{ip}, w_{pj})(0) = (z_{ip}, z_{pj}) \text{ 的解}$$

为

$$w_{ip} = z_{ip} \cos \theta + z_{pj} \sum_s (A_{ip}^{sj})' e'_t e_s \sin \theta,$$

$$w_{pj} = -z_{ip} \sum_s e'_s e_t A_{ip}^{sj} \sin \theta + z_{pj} \cos \theta.$$

所以, $\exp(\theta(X_{ij}^{(t)} - Z_{ij}^{(t)}))$ 可以表示为:

$$\begin{aligned} r_p &= s_p, \quad p \neq i, j, \\ r_i &= \left(\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_i + \left(-\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_j + \sin 2\theta z_{ij}^{(t)}, \\ r_j &= \left(-\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_i + \left(\frac{1}{2} \cos 2\theta + \frac{1}{2}\right) s_j - \sin 2\theta z_{ij}^{(t)}, \\ w_{ij}^{(s)} &= z_{ij}^{(s)}, \quad s \neq t, \\ w_{ij}^{(t)} &= -\frac{1}{2} \sin 2\theta s_i + \frac{1}{2} \sin 2\theta s_j + \cos 2\theta z_{ij}^{(t)}, \\ w_{pi} &= z_{pi} \cos \theta + z_{pj} \sum_s A_{pi}^{sj} e'_t e_s \sin \theta, \quad p < i, \\ w_{pj} &= -z_{pi} \sum_s e'_s e_t (A_{pi}^{sj})' \sin \theta + z_{pj} \cos \theta, \quad p < i, \\ w_{ip} &= z_{ip} \cos \theta + z_{pj} \sum_s (A_{ip}^{sj})' e'_t e_s \sin \theta, \quad i < p < j, \\ w_{pj} &= -z_{ip} \sum_s e'_s e_t A_{ip}^{sj} \sin \theta + z_{pj} \cos \theta, \quad i < p < j, \\ w_{ip} &= z_{ip} \cos \theta + z_{jp} (A_{ij}^{tp})' \sin \theta, \quad p > j, \\ w_{jp} &= -z_{ip} A_{ij}^{tp} \sin \theta + z_{jp} \cos \theta, \quad p > j, \\ v_p &= u_p, \quad p \neq i, j, \\ v_i &= u_i \cos \theta + \overline{u_j(Q_{ij}^{(t)})}' \sin \theta, \\ v_j &= -u_i Q_{ij}^{(t)} \sin \theta + u_j \cos \theta. \end{aligned}$$

$$\S 3.3 \quad \exp(\theta(Y_i^{(t)} - \tilde{P}_i^{(t)})), \quad \exp(\theta(\tilde{Y}_i^{(t)} + P_i^{(t)}))$$

在这一节, 我们计算 $Y_i^{(t)} - \tilde{P}_i^{(t)}, \tilde{Y}_i^{(t)} + P_i^{(t)}$ 所决定的单参数子群.

— 计算 $Y_i^{(t)} - \tilde{P}_i^{(t)}, i \in \{i_1, \dots, i_\rho\}$ 所决定的单参数子群 $\exp(\theta(Y_i^{(t)} - \tilde{P}_i^{(t)}))$.
由引理 2.5 列出满足零点初值为 (z, u) 的常微分方程组

$$\frac{dr_i}{d\theta} = 2\sqrt{-1}r_i v_i^{(t)} - 2v_i^{(t)},$$

$$\frac{dr_p}{d\theta} = 2\sqrt{-1} \sum_s w_{pi}^{(s)} v_p Q_{pi}^{(s)} e'_t, \quad p < i,$$

$$\frac{dr_p}{d\theta} = 2\sqrt{-1} \sum_s w_{ip}^{(s)} v_p \overline{Q_{ip}^{(s)}}' e'_t, \quad p > i,$$

$$\frac{dv_i}{d\theta} = 2\sqrt{-1}v_i^{(t)} v_i + r_i e_t - \sqrt{-1}e_t,$$

$$\frac{dv_p}{d\theta} = \sum_s [w_{pi}^{(s)} e_t \overline{Q_{pi}^{(s)}}' + \sqrt{-1}v_p Q_{pi}^{(s)} e'_t v_i \overline{Q_{pi}^{(s)}}'], \quad p < i,$$

$$\frac{dv_p}{d\theta} = \sum_s [w_{ip}^{(s)} e_t Q_{ip}^{(s)} + \sqrt{-1}v_p \overline{Q_{ip}^{(s)}}' e'_t v_i Q_{ip}^{(s)}], \quad p > i,$$

$$\frac{dw_{pi}}{d\theta} = \sqrt{-1} \sum_s (r_i + \sqrt{-1}) v_p Q_{pi}^{(s)} e'_t e_s + \sqrt{-1} \sum_{s,r} w_{pi}^{(s)} v_i \overline{Q_{pi}^{(r)}}' Q_{pi}^{(s)} e'_t e_r, \quad p < i,$$

$$\frac{dw_{ip}}{d\theta} = \sqrt{-1} \sum_s (r_i + \sqrt{-1}) v_p \overline{Q_{ip}^{(s)}}' e'_t e_s + \sqrt{-1} \sum_{s,r} w_{ip}^{(s)} v_i Q_{ip}^{(r)} \overline{Q_{ip}^{(s)}}' e'_t e_r, \quad p > i,$$

$$\frac{dw_{lp}}{d\theta} = \sqrt{-1} \sum_{s,u} [v_p Q_{pi}^{(s)} e'_t w_{li} A_{lp}^{ui} e'_s e_u + v_l Q_{li}^{(s)} e'_t e_s A_{lp}^{ui} w'_{pi} e_u], \quad l < p < i,$$

$$\frac{dw_{lp}}{d\theta} = \sqrt{-1} \sum_s v_l Q_{li}^{(s)} e'_t w_{ip} (A_{li}^{sp})' + \sqrt{-1} \sum_{s,u} w_{li}^{(u)} v_p \overline{Q_{ip}^{(s)}}' e'_t e_s (A_{li}^{up})', \quad l < i < p,$$

$$\frac{dw_{lp}}{d\theta} = \sqrt{-1} \sum_s v_l \overline{Q_{il}^{(s)}}' e'_t w_{ip} A_{il}^{sp} + \sqrt{-1} \sum_{s,u} w_{il}^{(u)} v_p \overline{Q_{ip}^{(s)}}' e'_t e_s A_{il}^{up}, \quad i < l < p.$$

下面求解这个常微分方程组.

(1) 先求 r_i .

由

$$\frac{dr_i}{d\theta} = 2\sqrt{-1}r_i v_i^{(t)} - 2v_i^{(t)},$$

得

$$\frac{d^2 r_i}{d\theta^2} = 2\sqrt{-1} \frac{dr_i}{d\theta} v_i^{(t)} + 2\sqrt{-1} r_i \frac{dv_i^{(t)}}{d\theta} - 2 \frac{dv_i^{(t)}}{d\theta}.$$

由 $\frac{dr_i}{d\theta} = 2\sqrt{-1}r_i v_i^{(t)} - 2v_i^{(t)}$, 可得

$$v_i^{(t)} = \frac{\frac{dr_i}{d\theta}}{2\sqrt{-1}(r_i + \sqrt{-1})},$$

由 $\frac{dv_i}{d\theta} = 2\sqrt{-1}v_i^{(t)}v_i + r_i e_t - \sqrt{-1}e_t$, 可得

$$\frac{dv_i^{(t)}}{d\theta} = 2\sqrt{-1}v_i^{(t)2} + r_i - \sqrt{-1}.$$

所以可列出满足初值条件的微分方程:

$$\begin{cases} \frac{d^2 r_i}{d\theta^2} = \frac{2}{r_i + \sqrt{-1}} \left(\frac{dr_i}{d\theta}\right)^2 + 2\sqrt{-1}(r_i^2 + 1) \\ r_i(0) = s_i \\ \frac{dr_i}{d\theta}(0) = 2\sqrt{-1}s_i u_i^{(t)} - 2u_i^{(t)} \end{cases}$$

令 $p = \frac{dr_i}{d\theta}$, 并以 r_i 为自变量, p 为新的未知函数, 可得:

$$p \frac{dp}{dr_i} = \frac{2}{r_i + \sqrt{-1}} p^2 + 2\sqrt{-1}(r_i + \sqrt{-1})(r_i - \sqrt{-1}),$$

令 $u = r_i + \sqrt{-1}$, 可得

$$p \frac{dp}{du} = \frac{2}{u} p^2 + 2\sqrt{-1}u(u - 2\sqrt{-1}),$$

令 $q = \frac{p}{u^2}$, 可得:

$$q dq = \frac{2\sqrt{-1}}{u^2} du + \frac{4}{u^3} du,$$

两边积分得

$$\begin{aligned} q^2 &= -\frac{4\sqrt{-1}}{u} - \frac{4}{u^2} + c, \\ p &= \frac{dr_i}{d\theta} = \frac{du}{d\theta}, \end{aligned} \tag{3.3.1}$$

所以,

$$\begin{aligned} \frac{du}{d\theta} &= u^2 \sqrt{c - \frac{4\sqrt{-1}}{u} - \frac{4}{u^2}}, \\ \frac{-d\frac{1}{u}}{\sqrt{c - \frac{4\sqrt{-1}}{u} - \frac{4}{u^2}}} &= d\theta. \end{aligned}$$

令

$$x = \frac{1}{u} = \frac{1}{r_i + \sqrt{-1}},$$

则

$$\frac{dx}{\sqrt{c - 4\sqrt{-1}x - 4x^2}} = -d\theta,$$

$$\begin{aligned} \frac{\frac{1}{2}d\frac{2}{\sqrt{c-1}}(x + \frac{\sqrt{-1}}{2})}{\sqrt{1 - [\frac{2}{\sqrt{c-1}}(x + \frac{\sqrt{-1}}{2})]^2}} &= -d\theta, \\ \arcsin \frac{2}{\sqrt{c-1}}(x + \frac{\sqrt{-1}}{2}) &= -2\theta - c', \\ x &= -\frac{\sqrt{c-1}}{2} \sin(2\theta + c') - \frac{\sqrt{-1}}{2}, \end{aligned} \quad (3.3.2)$$

所以

$$r_i = -\frac{2}{\sqrt{c-1} \sin(2\theta + c') + \sqrt{-1}} - \sqrt{-1}.$$

在 (3.3.1) 式和 (3.3.2) 式中, 令 $\theta = 0$, 得

$$c = \frac{4\sqrt{-1}s_i - 4u_i^{(t)2}}{(s_i + \sqrt{-1})^2}, \quad c' = \operatorname{arctg} \frac{\sqrt{-1} - s_i}{2u_i^{(t)}}.$$

(2) 求 v_i .

由

$$\frac{dv_i}{d\theta} = 2\sqrt{-1}v_i^{(t)}v_i + r_i e_t - \sqrt{-1}e_t,$$

得

$$\begin{aligned} \frac{d^2v_i}{d\theta^2} &= 2\sqrt{-1}v_i^{(t)} \frac{dv_i}{d\theta} + 2\sqrt{-1} \frac{dv_i^{(t)}}{d\theta} v_i + \frac{dr_i}{d\theta} e_t \\ &= 2\sqrt{-1}v_i^{(t)} (2\sqrt{-1}v_i^{(t)}v_i + r_i e_t - \sqrt{-1}e_t) \\ &\quad + 2\sqrt{-1}(2\sqrt{-1}v_i^{(t)2} + r_i - \sqrt{-1})v_i + (2\sqrt{-1}r_i v_i^{(t)} - 2v_i^{(t)})e_t \\ &= -8v_i^{(t)2}v_i + 4\sqrt{-1}v_i^{(t)}r_i e_t + 2\sqrt{-1}(r_i - \sqrt{-1})v_i \\ &= 4\sqrt{-1}v_i^{(t)}(2\sqrt{-1}v_i^{(t)}v_i + r_i e_t - \sqrt{-1}e_t) + 2\sqrt{-1}(r_i - \sqrt{-1})v_i - 4v_i^{(t)}e_t \\ &= 4\sqrt{-1}v_i^{(t)} \frac{dv_i}{d\theta} + 2\sqrt{-1}(r_i - \sqrt{-1})v_i - 4v_i^{(t)}e_t. \end{aligned}$$

令 $f(\theta) = \sqrt{c-1} \sin(2\theta + c') + \sqrt{-1}$, 可以得到下面重要的关系式

$$\begin{aligned} r_i + \sqrt{-1} &= -\frac{2}{f(\theta)}, \\ f''(\theta) &= 4\sqrt{-1} - 4f(\theta), \\ v_i^{(t)} &= \frac{\frac{dr_i}{d\theta}}{2\sqrt{-1}(r_i + \sqrt{-1})} = -\frac{f'(\theta)}{2\sqrt{-1}f(\theta)}. \end{aligned}$$

$$\frac{d^2v_i}{d\theta^2} = -2\frac{f'(\theta)}{f(\theta)} \frac{dv_i}{d\theta} - 4\sqrt{-1} \frac{1}{f(\theta)} v_i + 4v_i - 2\sqrt{-1} \frac{f'(\theta)}{f(\theta)} e_t,$$

即

$$f(\theta) \frac{d^2 v_i}{d\theta^2} = -2f'(\theta) \frac{dv_i}{d\theta} - f''(\theta)v_i - 2\sqrt{-1}f'(\theta)e_t.$$

$$(f(\theta)v_i)'' = -2\sqrt{-1}f'(\theta)e_t,$$

所以

$$v_i = \frac{\sqrt{-1}\sqrt{c-1}\cos(2\theta+c')e_t + (2e_t+c_1)\theta + c_2}{\sqrt{c-1}\sin(2\theta+c') + \sqrt{-1}}, \quad (3.3.3)$$

由 (3.3.3) 式及初值条件 $v_i(0) = u_i$ 可得

$$c_1 = -2e_t, \quad c_2 = \frac{-2u_i + 2u_i^{(t)}e_t}{s_i + \sqrt{-1}}.$$

所以

$$v_i = \frac{\sqrt{-1}\sqrt{c-1}\cos(2\theta+c')e_t + c_2}{\sqrt{c-1}\sin(2\theta+c') + \sqrt{-1}}, \quad c_2 = \frac{-2u_i + 2u_i^{(t)}e_t}{s_i + \sqrt{-1}}.$$

(3) $w_{pi}(p < i)$ 和 $w_{ip}(p > i)$ 的求法相同, 这里只写出 $w_{pi}(p < i)$ 的求法.
由

$$\frac{dw_{pi}}{d\theta} = \sqrt{-1} \sum_s (r_i + \sqrt{-1})v_p Q_{pi}^{(s)} e'_t e_s + \sqrt{-1} \sum_{s,r} w_{pi}^{(s)} v_i(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r,$$

得

$$\begin{aligned} \frac{d^2 w_{pi}}{d\theta^2} &= \sqrt{-1} \sum_s \frac{dr_i}{d\theta} v_p Q_{pi}^{(s)} e'_t e_s + \sqrt{-1} \sum_s (r_i + \sqrt{-1}) \frac{dv_p}{d\theta} Q_{pi}^{(s)} e'_t e_s \\ &+ \sqrt{-1} \sum_{s,r} \frac{dw_{pi}^{(s)}}{d\theta} v_i(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r + \sqrt{-1} \sum_{s,r} w_{pi}^{(s)} \frac{dv_i}{d\theta}(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r \\ &= - \sum_{s,r} (r_i + \sqrt{-1}) v_p Q_{pi}^{(r)} e'_t v_i(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_s \\ &+ \sqrt{-1} \sum_{s,r} (r_i + \sqrt{-1}) w_{pi}^{(s)} e_t(\overline{Q_{pi}^{(s)}})' Q_{pi}^{(r)} e'_t e_r - 2 \sum_s (r_i + \sqrt{-1}) v_i^{(t)} v_p Q_{pi}^{(s)} e'_t e_s \\ &- 2 \sum_{s,r} v_i^{(t)} w_{pi}^{(s)} v_i(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r + \sqrt{-1} \sum_{s,r} w_{pi}^{(s)} (r_i - \sqrt{-1}) e_t(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r \\ &- \sum_{s,r} (r_i + \sqrt{-1}) v_i(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t v_p Q_{pi}^{(s)} e'_t e_r - \sum_{s,r,l} w_{pi}^{(l)} v_i(\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t v_i(\overline{Q_{pi}^{(s)}})' Q_{pi}^{(l)} e'_t e_r \end{aligned}$$

$$\begin{aligned}
&= (r_i + \sqrt{-1}) \sum_{s,r} v_p Q_{pi}^{(r)} e'_t v_i (\overline{Q_{pi}^{(s)}})' Q_{pi}^{(r)} e'_t e_s - 2(r_i + \sqrt{-1}) \sum_s v_p Q_{pi}^{(s)} e'_t v_i e'_t e_s \\
&\quad - \sqrt{-1} \sum_{s,r} (r_i + \sqrt{-1}) w_{pi}^{(s)} e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r + 2\sqrt{-1} \sum_s (r_i + \sqrt{-1}) w_{pi}^{(s)} e_t e'_t e_s \\
&\quad - 2(r_i + \sqrt{-1}) \sum_s v_i^{(t)} v_p Q_{pi}^{(s)} e'_t e_s - 2 \sum_{s,r} v_i^{(t)} w_{pi}^{(s)} v_i (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r \\
&\quad + \sqrt{-1} \sum_{s,r} (r_i - \sqrt{-1}) w_{pi}^{(s)} e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r - \sum_{s,r} (r_i + \sqrt{-1}) v_i (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_t Q_{pi}^{(s)'} v_p' e_r \\
&\quad + \sum_{s,r,l} w_{pi}^{(l)} v_i (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t v_i (\overline{Q_{pi}^{(l)}})' Q_{pi}^{(s)} e'_t e_r - 2 \sum_{s,r} w_{pi}^{(s)} v_i (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t v_i e'_t e_r \\
&= -4(r_i + \sqrt{-1}) \sum_s v_p Q_{pi}^{(s)} v_i^{(t)} e'_t e_s + 2\sqrt{-1}(r_i + \sqrt{-1}) w_{pi} \\
&\quad - 4 \sum_{s,r} v_i^{(t)} w_{pi}^{(s)} v_i (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r + 2 \sum_{s,r} w_{pi}^{(s)} e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r \\
&= 4\sqrt{-1} v_i^{(t)} \frac{dw_{pi}}{d\theta} + 2\sqrt{-1}(r_i + \sqrt{-1}) w_{pi} + 2 \sum_{s,r} w_{pi} e'_s e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r
\end{aligned}$$

所以可列出满足初值条件的微分方程

$$\begin{cases} \frac{d^2 w_{pi}}{d\theta^2} = 4\sqrt{-1} v_i^{(t)} \frac{dw_{pi}}{d\theta} + 2\sqrt{-1}(r_i + \sqrt{-1}) w_{pi} + 2 \sum_{s,r} w_{pi} e'_s e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r \\ w_{pi}(0) = z_{pi}, \\ \frac{dw_{pi}}{d\theta}(0) = \sqrt{-1} \sum_s (s_i + \sqrt{-1}) v_p Q_{pi}^{(s)} e'_t e_s + \sqrt{-1} \sum_{s,r} z_{pi}^{(s)} v_i (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r \end{cases}$$

$$\frac{d^2 w_{pi}}{d\theta^2} = 4\sqrt{-1} \left(-\frac{f'(\theta)}{2\sqrt{-1}f(\theta)} \right) \frac{dw_{pi}}{d\theta} + 2\sqrt{-1} \frac{-2}{f(\theta)} w_{pi} + 2w_{pi} \sum_{s,r} e'_s e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r,$$

$$f(\theta) \frac{d^2 w_{pi}}{d\theta^2} = -2f'(\theta) \frac{dw_{pi}}{d\theta} - 4\sqrt{-1} w_{pi} + 2f(\theta) w_{pi} \sum_{s,r} e'_s e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r,$$

$$\begin{aligned}
(f(\theta) w_{pi})'' &= -4f(\theta) w_{pi} + 2f(\theta) w_{pi} \sum_{s,r} e'_s e_t (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e'_t e_r \\
&= -2f(\theta) w_{pi} \sum_{s,r} e'_s e_t (\overline{Q_{pi}^{(s)}})' Q_{pi}^{(r)} e'_t e_r,
\end{aligned}$$

令

$$x = f(\theta) w_{pi}, \quad K_{pi}^{(t)} = \sum_r Q_{pi}^{(r)} e'_t e_r,$$

则

$$x'' = -2x (\overline{K_{pi}^{(t)}})' K_{pi}^{(t)},$$

$H = \overline{(K_{pi}^{(t)})' K_{pi}^{(t)}}$ 为正定的 Hermite 矩阵, 所以, 存在酉矩阵 U_{pi} , 使得 $\overline{U_{pi}'} H U_{pi}$ 是对角阵 $\{\lambda_{pi}^{(s)}\}$, $\lambda_{pi}^{(s)} \in \mathbb{R}^+$, $s = 1, \dots, n_{pi}$ 为矩阵 H 的特征值.

$$\frac{d^2 x}{d\theta^2} = -2xH = -2xU_{pi} \begin{pmatrix} \lambda_{pi}^{(1)} & & \\ & \dots & \\ & & \lambda_{pi}^{(n_{pi})} \end{pmatrix} \overline{U_{pi}'},$$

令 $y = xU_{pi}$, 则

$$\frac{d^2 y}{d\theta^2} = -2y \begin{pmatrix} \lambda_{pi}^{(1)} & & \\ & \dots & \\ & & \lambda_{pi}^{(n_{pi})} \end{pmatrix},$$

记: $y = (y_1, y_2, \dots, y_{n_{pi}})$, 而 $\frac{d^2 y_s}{d\theta^2} = -2\lambda_{pi}^{(s)} y_s$ 的解为

$$y_s = c_{pi}^{(s)} \sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'}),$$

$$xU_{pi} = f(\theta)w_{pi}U_{pi} = y = \sum_s y_s e_s = \sum_s c_{pi}^{(s)} \sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'}) e_s,$$

所以

$$w_{pi} = \frac{\sum_s c_{pi}^{(s)} \sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'}) e_s \overline{U_{pi}'}}{f(\theta)}. \quad (3.3.4)$$

由 (3.3.4) 式及初值条件得

$$c_{pi}^{(s)'} = \operatorname{arctg} \sqrt{2\lambda_{pi}^{(s)}} \frac{x(0)U_{pi}e_s'}{x'(0)U_{pi}e_s'}, \quad c_{pi}^{(s)} = \frac{f(0)z_{pi}U_{pi}e_s'}{\sin c_{pi}^{(s)'}}.$$

所以

$$w_{pi} = \frac{1}{f(\theta)} \sum_s \frac{\sin(\sqrt{2\lambda_{pi}^{(s)}} \theta + c_{pi}^{(s)'})}{\sin c_{pi}^{(s)'}} f(0)z_{pi}U_{pi}e_s' e_s \overline{U_{pi}'},$$

$$c_{pi}^{(s)'} = \operatorname{arctg} \frac{\sqrt{2\lambda_{pi}^{(s)}} f(0)z_{pi}U_{pi}e_s'}{(\sqrt{-1}f(0)(\sum_s (s_i + \sqrt{-1})u_p Q_{pi}^{(s)} e_t' e_s + \sum_{s,r} z_{pi}^{(s)} u_i (\overline{Q_{pi}^{(r)}})' Q_{pi}^{(s)} e_t' e_r) + f'(0)z_{pi})U_{pi}e_s'}$$

(4) $r_p(p < i)$ 和 $r_p(p > i)$ 的求法相同, 下面只写出 $r_p(p < i)$ 的求法.

由

$$\frac{dr_p}{d\theta} = 2\sqrt{-1} \sum_s w_{pi}^{(s)} v_p Q_{pi}^{(s)} e_t',$$

得

$$\begin{aligned}
\frac{d^2 r_p}{d\theta^2} &= 2\sqrt{-1} \sum_s \frac{dw_{pi}^{(s)}}{d\theta} v_p Q_{pi}^{(s)} e'_t + 2\sqrt{-1} \sum_s w_{pi}^{(s)} \frac{dv_p}{d\theta} Q_{pi}^{(s)} e'_t \\
&= -2 \sum_s (r_i + \sqrt{-1}) v_p Q_{pi}^{(s)} e'_t v_p Q_{pi}^{(s)} e'_t - 2 \sum_{s,l} w_{pi}^{(l)} v_i \overline{(Q_{pi}^{(s)})'} Q_{pi}^{(l)} e'_t v_p Q_{pi}^{(s)} e'_t \\
&\quad + 2\sqrt{-1} \sum_{s,l} w_{pi}^{(s)} w_{pi}^{(l)} e_t \overline{(Q_{pi}^{(l)})'} Q_{pi}^{(s)} e'_t - 2 \sum_{s,l} w_{pi}^{(s)} v_p Q_{pi}^{(l)} e'_t v_i \overline{(Q_{pi}^{(l)})'} Q_{pi}^{(s)} e'_t \\
&= -8v_i^{(t)} \sum_s w_{pi}^{(s)} v_p Q_{pi}^{(s)} e'_t + 2\sqrt{-1} w_{pi} w'_{pi} \\
&= 4\sqrt{-1} v_i^{(t)} \frac{dr_p}{d\theta} + 2\sqrt{-1} w_{pi} w'_{pi} \\
&= 4\sqrt{-1} \left(-\frac{f'(\theta)}{2\sqrt{-1}f(\theta)} \right) \frac{dr_p}{d\theta} + 2\sqrt{-1} w_{pi} w'_{pi},
\end{aligned}$$

所以

$$\begin{aligned}
f^2(\theta) \frac{d^2 r_p}{d\theta^2} &= -2f(\theta)f'(\theta) \frac{dr_p}{d\theta} + 2\sqrt{-1}f^2(\theta)w_{pi}w'_{pi}, \\
(f^2(\theta) \frac{dr_p}{d\theta})' &= 2\sqrt{-1}f^2(\theta)w_{pi}w'_{pi},
\end{aligned}$$

将已求得的 w_{pi} 代入得

$$\begin{aligned}
r_p &= \sum_{s,r} \frac{2\sqrt{-1}f^2(0)z_{pi}U_{pi}E_{ss}\bar{U}_{pi}'\bar{U}_{pi}E_{rr}U_{pi}'z'_{pi}}{\sin c_{pi}^{(s)'} \sin c_{pi}^{(r)'}} \\
&\quad \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(s)}}\theta + c_{pi}^{(s)'}) \sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) d\theta \right) d\theta,
\end{aligned}$$

待定参数由初值 $r_p(0) = s_p$, $\frac{dr_p}{d\theta}(0) = 2\sqrt{-1} \sum_s z_{pi}^{(s)} v_p Q_{pi}^{(s)} e'_t$ 确定.

(5) $v_p(p < i)$ 和 $v_p(p > i)$ 的求法相同, 下面只写出 $v_p(p < i)$ 的求法.

$$\frac{dv_p}{d\theta} = \sum_s [w_{pi}^{(s)} e_t \overline{(Q_{pi}^{(s)})'} + \sqrt{-1} v_p Q_{pi}^{(s)} e'_t v_i \overline{(Q_{pi}^{(s)})'}], \quad p < i,$$

由 $\frac{dw_{pi}^{(s)}}{d\theta} = \sqrt{-1}(r_i + \sqrt{-1})v_p Q_{pi}^{(s)} e'_t + \sqrt{-1} \sum_l w_{pi}^{(l)} v_i \overline{(Q_{pi}^{(s)})'} Q_{pi}^{(l)} e'_t$, $r_i + \sqrt{-1} = -\frac{2}{f(\theta)}$, 得

$$\sqrt{-1} v_p Q_{pi}^{(s)} e'_t = \frac{\sqrt{-1}}{2} f(\theta) \sum_l w_{pi}^{(l)} v_i \overline{(Q_{pi}^{(s)})'} Q_{pi}^{(l)} e'_t - \frac{1}{2} f(\theta) \frac{dw_{pi}^{(s)}}{d\theta},$$

$$\begin{aligned}\frac{dv_p}{d\theta} &= \sum_s [w_{pi}^{(s)} e_t(Q_{pi}^{(s)}) + \frac{\sqrt{-1}}{2} f(\theta) \sum_l w_{pi}^{(l)} v_i(Q_{pi}^{(s)}) Q_{pi}^{(l)} e_t' v_i(Q_{pi}^{(s)}) - \frac{1}{2} f(\theta) \frac{dw_{pi}^{(s)}}{d\theta} v_i(Q_{pi}^{(s)})] \\ &= \sum_s [w_{pi}^{(s)} e_t(Q_{pi}^{(s)}) - \frac{1}{2} f(\theta) \frac{dw_{pi}^{(s)}}{d\theta} v_i(Q_{pi}^{(s)})],\end{aligned}$$

将以求得的 $w_{pi}^{(s)}$, v_i 代入得

$$\begin{aligned}v_p &= \sum_{s,r} f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' E_{st}(Q_{pi}^{(s)}) \int \frac{\sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'})}{\sin c_{pi}^{(r)'} f(\theta)} d\theta - \frac{1}{2} \sum_{s,r} f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' e_s' \\ &\quad \cdot \left(\int \frac{\sqrt{2\lambda_{pi}^{(r)}} \cos(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) f(\theta) - \sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) f'(\theta)}{\sin c_{pi}^{(r)'} f^2(\theta)} \right. \\ &\quad \left. (\sqrt{-1}\sqrt{c-1} \cos(2\theta + c') e_t + c_2) d\theta \right) (Q_{pi}^{(s)})',\end{aligned}$$

待定参数由初值 $v_p(0) = u_p$ 确定.

(6) 求 $w_{lp}(l < p < i)$, $w_{lp}(l < i < p)$ 和 $w_{lp}(l < p < i)$ 求法相同, 下面只写出 $w_{lp}(l < p < i)$ 的求法.

由

$$\frac{dw_{lp}}{d\theta} = \sqrt{-1} \sum_{s,u} [v_p Q_{pi}^{(s)} e_t' w_{li} A_{lp}^{ui} e_s' e_u + v_l Q_{li}^{(s)} e_t' e_s A_{lp}^{ui} w_{pi}' e_u],$$

得

$$\begin{aligned}\frac{d^2 w_{lp}}{d\theta^2} &= \sqrt{-1} \sum_{s,u} \frac{dv_p}{d\theta} Q_{pi}^{(s)} e_t' w_{li} A_{lp}^{ui} e_s' e_u + \sqrt{-1} \sum_{s,u} v_p Q_{pi}^{(s)} e_t' \frac{dw_{li}}{d\theta} A_{lp}^{ui} e_s' e_u \\ &\quad + \sqrt{-1} \sum_{s,u} \frac{dv_l}{d\theta} Q_{li}^{(s)} e_t' e_s A_{lp}^{ui} w_{pi}' e_u + \sqrt{-1} \sum_{s,u} v_l Q_{li}^{(s)} e_t' e_s A_{lp}^{ui} \frac{dw_{pi}'}{d\theta} e_u \\ &= - \sum_{s,r,u} v_p Q_{pi}^{(r)} e_t' v_i(Q_{pi}^{(r)}) Q_{pi}^{(s)} e_t' w_{li} A_{lp}^{ui} e_s' e_u + \sqrt{-1} \sum_{s,r,u} w_{pi}^{(r)} e_t(Q_{pi}^{(r)}) Q_{pi}^{(s)} e_t' w_{li} A_{lp}^{ui} e_s' e_u \\ &\quad - (r_i + \sqrt{-1}) \sum_{s,r,u} v_p Q_{pi}^{(s)} e_t' v_l Q_{li}^{(r)} e_t' e_r A_{lp}^{ui} e_s' e_u - \sum_{s,r,u,h} w_{li}^{(h)} v_p Q_{pi}^{(s)} e_t' v_i(Q_{li}^{(r)}) Q_{li}^{(h)} e_t' e_r A_{lp}^{ui} e_s' e_u \\ &\quad - \sum_{s,r,u} v_l Q_{li}^{(r)} e_t' v_i(Q_{li}^{(r)}) Q_{li}^{(s)} e_t' e_s A_{lp}^{ui} w_{pi}' e_u + \sqrt{-1} \sum_{s,r,u} w_{li}^{(r)} e_t(Q_{li}^{(r)}) Q_{li}^{(s)} e_t' e_s A_{lp}^{ui} w_{pi}' e_u \\ &\quad - (r_i + \sqrt{-1}) \sum_{s,r,u} v_l Q_{li}^{(s)} e_t' e_s A_{lp}^{ui} e_r' v_p Q_{pi}^{(r)} e_t' e_u - \sum_{s,r,u,h} w_{pi}^{(h)} v_l Q_{li}^{(s)} e_t' e_s A_{lp}^{ui} e_r' v_i(Q_{pi}^{(r)}) Q_{pi}^{(h)} e_t' e_u\end{aligned}$$

$$\begin{aligned}
&= -2v_i^{(t)} \sum_{s,u} v_p Q_{pi}^{(s)} e'_t w_{li} A_{lp}^{ui} e'_s e_u + \sqrt{-1} \sum_{s,r,u} w_{pi}^{(r)} e_t \overline{(Q_{pi}^{(r)})'} Q_{pi}^{(s)} e'_t w_{li} A_{lp}^{ui} e'_s e_u \\
&\quad - \sum_{s,r,u} v_p Q_{pi}^{(s)} e'_t v_i \overline{(Q_{pi}^{(s)})'} Q_{pi}^{(r)} e'_t w_{li} A_{lp}^{ui} e'_r e_u - 2v_i^{(t)} \sum_{s,u} v_l Q_{li}^{(s)} e'_t e_s A_{lp}^{ui} w'_{pi} e_u \\
&\quad + \sqrt{-1} \sum_{s,r,u,h} w_{li}^{(r)} w_{pi}^{(h)} e_t \overline{(Q_{pi}^{(s)})'} Q_{pi}^{(h)} e'_t e_r A_{lp}^{ui} e'_s e_u - \sum_{s,r,u} w_{pi}^{(s)} v_l Q_{lp}^{(u)} Q_{pi}^{(r)} e'_t v_i \overline{(Q_{pi}^{(r)})'} Q_{pi}^{(s)} e'_t e_u \\
&= -4v_i^{(t)} \sum_{s,u} (v_p Q_{pi}^{(s)} e'_t w_{li} A_{lp}^{ui} e'_s e_u + v_l Q_{li}^{(s)} e'_t e_s A_{lp}^{ui} w'_{pi} e_u) + 2\sqrt{-1} \sum_{s,u} w_{pi}^{(s)} w_{li} A_{lp}^{ui} e'_s e_u \\
&= 4\sqrt{-1} v_i^{(t)} \frac{dw_{lp}}{d\theta} + 2\sqrt{-1} \sum_{s,u} w_{pi}^{(s)} w_{li} A_{lp}^{ui} e'_s e_u
\end{aligned}$$

以上计算利用了公式

$$\begin{aligned}
\sum_r e_r A_{lp}^{ui} e'_s Q_{li}^{(r)} &= Q_{lp}^{(u)} Q_{pi}^{(s)}, \\
\sum_s e_h A_{lp}^{ui} e'_s Q_{pi}^{(s)} &= \overline{(Q_{lp}^{(u)})'} Q_{li}^{(h)}.
\end{aligned}$$

所以

$$\begin{aligned}
\frac{d^2 w_{lp}}{d\theta^2} &= -2 \frac{f'(\theta)}{f(\theta)} \frac{dw_{lp}}{d\theta} + 2\sqrt{-1} \sum_{s,u} w_{pi}^{(s)} w_{li} A_{lp}^{ui} e'_s e_u, \\
f^2(\theta) \frac{d^2 w_{lp}}{d\theta^2} + 2f(\theta) f'(\theta) \frac{dw_{lp}}{d\theta} &= 2\sqrt{-1} f^2(\theta) \sum_{s,u} w_{pi}^{(s)} w_{li} A_{lp}^{ui} e'_s e_u, \\
(f^2(\theta) \frac{dw_{lp}}{d\theta})' &= 2\sqrt{-1} f^2(\theta) \sum_{s,u} w_{pi}^{(s)} w_{li} A_{lp}^{ui} e'_s e_u,
\end{aligned}$$

将已求得的 $w_{pi}^{(s)}$, w_{li} 代入得

$$\begin{aligned}
w_{lp} &= \sum_{s,r,u,h} \frac{2\sqrt{-1} f^2(0) z_{pi} U_{pi} E_{rr} \overline{U_{pi}'} e'_s z_{li} U_{li} E_{hh} \overline{U_{li}'}}{\sin c_{pi}^{(r)'} \sin c_{li}^{(h)'}} \\
&\quad \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(r)}} \theta + c_{pi}^{(r)'}) \sin(\sqrt{2\lambda_{li}^{(h)}} \theta + c_{li}^{(h)'}) A_{lp}^{ui} e'_s e_u d\theta \right) d\theta,
\end{aligned}$$

待定参数由初值条件

$$w_{lp}(0) = z_{lp}, \quad \frac{dw_{lp}}{d\theta}(0) = \sqrt{-1} \sum_{s,u} [u_p Q_{pi}^{(s)} e'_t z_{li} A_{lp}^{ui} e'_s e_u + u_l Q_{li}^{(s)} e'_t e_s A_{lp}^{ui} z'_{pi} e_u]$$

确定.

综上所述, $\exp(\theta(Y_i^{(t)} - \bar{P}_i^{(t)}))$ 可表示为:

$$r_i = -\frac{2}{f(\theta)} - \sqrt{-1},$$

$$v_i = \frac{\sqrt{-1}\sqrt{c-1}\cos(2\theta + c')e_t + c_2}{f(\theta)},$$

$$w_{pi} = \frac{1}{f(\theta)} \sum_s \frac{\sin(\sqrt{2\lambda_{pi}^{(s)}}\theta + c_{pi}^{(s)'})}{\sin c_{pi}^{(s)'}} f(0) z_{pi} U_{pi} e'_s e_s \bar{U}_{pi}', \quad p < i,$$

$$w_{ip} = \frac{1}{f(\theta)} \sum_r \frac{\sin(\sqrt{2\mu_{ip}^{(r)}}\theta + c_{ip}^{(r)'})}{\sin c_{ip}^{(r)'}} f(0) z_{ip} U_{ip} e'_r e_r \bar{U}_{ip}', \quad p > i,$$

$$r_p = \sum_{s,r} \frac{2\sqrt{-1}f^2(0)z_{pi}U_{pi}E_{ss}\bar{U}_{pi}'\bar{U}_{pi}E_{rr}U_{pi}'z'_{pi}}{\sin c_{pi}^{(s)'}\sin c_{pi}^{(r)'}} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(s)}}\theta + c_{pi}^{(s)'}) \sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) d\theta \right) d\theta, \quad p < i,$$

$$r_p = \sum_{s,r} \frac{2\sqrt{-1}f^2(0)z_{ip}U_{ip}E_{ss}\bar{U}_{ip}'\bar{U}_{ip}E_{rr}U_{ip}'z'_{ip}}{\sin c_{ip}^{(s)'}\sin c_{ip}^{(r)'}} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\mu_{ip}^{(s)}}\theta + c_{ip}^{(s)'}) \sin(\sqrt{2\mu_{ip}^{(r)}}\theta + c_{ip}^{(r)'}) d\theta \right) d\theta, \quad p > i,$$

$$v_p = \sum_{s,r} f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' E_{st} \overline{Q_{pi}^{(s)'}} \int \frac{\sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'})}{\sin c_{pi}^{(r)'}} f(\theta) d\theta - \frac{1}{2} \sum_{s,r} f(0) z_{pi} U_{pi} E_{rr} \bar{U}_{pi}' e'_s e_s \cdot \left(\int \frac{\sqrt{2\lambda_{pi}^{(r)}} \cos(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) f(\theta) - \sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) f'(\theta)}{\sin c_{pi}^{(r)'}} f^2(\theta) \right. \\ \left. (\sqrt{-1}\sqrt{c-1}\cos(2\theta + c')e_t + c_2) d\theta \right) \overline{Q_{pi}^{(s)'}}, \quad p < i,$$

$$v_p = \sum_{s,r} f(0) z_{ip} U_{ip} E_{rr} \bar{U}_{ip}' E_{st} Q_{ip}^{(s)} \int \frac{\sin(\sqrt{2\mu_{ip}^{(r)}}\theta + c_{ip}^{(r)'})}{\sin c_{ip}^{(r)'}} f(\theta) d\theta - \frac{1}{2} \sum_{s,r} f(0) z_{ip} U_{ip} E_{rr} \bar{U}_{ip}' e'_s e_s \cdot \left(\int \frac{\sqrt{2\mu_{ip}^{(r)}} \cos(\sqrt{2\mu_{ip}^{(r)}}\theta + c_{ip}^{(r)'}) f(\theta) - \sin(\sqrt{2\mu_{ip}^{(r)}}\theta + c_{ip}^{(r)'}) f'(\theta)}{\sin c_{ip}^{(r)'}} f^2(\theta) \right. \\ \left. (\sqrt{-1}\sqrt{c-1}\cos(2\theta + c')e_t + c_2) d\theta \right) Q_{ip}^{(s)}, \quad p > i,$$

$$w_{lp} = \sum_{s,r,u,h} \frac{2\sqrt{-1}f^2(0)z_{pi}U_{pi}E_{rr}\bar{U}_{pi}'e'_s z_{li}U_{li}E_{hh}\bar{U}_{li}'A_{lp}^{ui}e'_s e_u}{\sin c_{pi}^{(r)'}\sin c_{li}^{(h)'}} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{pi}^{(r)}}\theta + c_{pi}^{(r)'}) \sin(\sqrt{2\lambda_{li}^{(h)}}\theta + c_{li}^{(h)'}) d\theta \right) d\theta, \quad l < p < i,$$

$$w_{lp} = \sum_{s,r,u} \frac{2\sqrt{-1}f^2(0)z_{li}U_{li}E_{rr}\bar{U}_{li}'e'_s z_{ip}U_{ip}E_{uu}\bar{U}_{ip}'(A_{li}^{sp})'}{\sin c'_{li(r)} \sin c_{ip}^{(u)'}} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\lambda_{li}^{(r)}}\theta + c_{li}^{(r)'}) \sin(\sqrt{2\mu_{ip}^{(u)}}\theta + c_{ip}^{(u)'}) d\theta \right) d\theta, \quad l < i < p,$$

$$w_{lp} = \sum_{s,r,u} \frac{2\sqrt{-1}f^2(0)z_{il}U_{il}E_{rr}\bar{U}_{il}'e'_s z_{ip}U_{ip}E_{uu}\bar{U}_{ip}'A_{il}^{sp}}{\sin c_{il}^{(r)' } \sin c_{ip}^{(u)'}} \cdot \int \left(\frac{1}{f^2(\theta)} \int \sin(\sqrt{2\mu_{il}^{(r)}}\theta + c_{il}^{(r)'}) \sin(\sqrt{2\mu_{ip}^{(u)}}\theta + c_{ip}^{(u)'}) d\theta \right) d\theta, \quad i < l < p.$$

其中

$$c = \frac{4\sqrt{-1}s_i - 4u_i^{(t)^2}}{(s_i + \sqrt{-1})^2}, \quad c' = \operatorname{arctg} \frac{\sqrt{-1} - s_i}{2u_i^{(t)}}, \quad f(\theta) = \sqrt{c-1} \sin(2\theta + c') + \sqrt{-1};$$

在 v_i 的表达式中, $c_2 = \frac{-2u_i + 2u_i^{(t)}e_t}{s_i + \sqrt{-1}}$;

在 w_{pi} 的表达式中, 酉矩阵 U_{pi} 使 Hermite 矩阵 $H = \sum_{s,r} e'_s e_t (Q_{pi}^{(s)})' Q_{pi}^{(r)} e'_t e_r$ 对角化, $\lambda_{pi}^{(s)}$, $s = 1, \dots, n_{pi}$ 为 H 的特征值,

$$c_{pi}^{(s)'} = \operatorname{arctg} \frac{\sqrt{2\lambda_{pi}^{(s)}} f(0) z_{pi} U_{pi} e'_s}{(\sqrt{-1}f(0)(\sum_s (s_i + \sqrt{-1})u_p Q_{pi}^{(s)} e'_t e_s + \sum_{s,r} z_{pi}^{(s)} u_i (Q_{pi}^{(r)})' Q_{pi}^{(s)} e'_t e_r) + f'(0)z_{pi})U_{pi} e'_s};$$

在 w_{ip} 的表达式中, 酉矩阵 U_{ip} 使 Hermite 矩阵 $M = \sum_{s,r} e'_s e_t Q_{ip}^{(s)} (Q_{ip}^{(r)})' e'_t e_r$ 对角化, $\mu_{ip}^{(r)}$, $r = 1, \dots, n_{ip}$ 为 M 的特征值,

$$c_{ip}^{(r)'} = \operatorname{arctg} \frac{\sqrt{2\mu_{ip}^{(r)}} f(0) z_{ip} U_{ip} e'_r}{(\sqrt{-1}f(0)(\sum_s (s_i + \sqrt{-1})u_p (Q_{ip}^{(s)})' e'_t e_s + \sum_{s,r} z_{ip}^{(s)} u_i Q_{ip}^{(r)} (Q_{ip}^{(s)})' e'_t e_r) + f'(0)z_{ip})U_{ip} e'_r};$$

在 $r_p(p < i)$ 的表达式中, 待定参数由初值 $r_p(0) = s_p$, $\frac{dr_p}{d\theta}(0) = 2\sqrt{-1} \sum_s z_{pi}^{(s)} u_p Q_{pi}^{(s)} e'_t$ 确定;

在 $r_p(p > i)$ 的表达式中, 待定参数由初值 $r_p(0) = s_p$, $\frac{dr_p}{d\theta}(0) = 2\sqrt{-1} \sum_s z_{ip}^{(s)} u_p (Q_{ip}^{(s)})' e'_t$ 确定;

在 $v_p(p < i)$ 的表达式中, 待定参数由初值 $v_p(0) = u_p$ 确定;

在 $v_p(p > i)$ 的表达式中, 待定参数由初值 $v_p(0) = u_p$ 确定;

在 $w_{lp}(l < p < i)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,

$\frac{dw_{lp}}{d\theta}(0) = \sqrt{-1} \sum_{s,u} [u_p Q_{pi}^{(s)} e'_t z_{li} A_{lp}^{ui} e'_s e_u + u_l Q_{li}^{(s)} e'_t e_s A_{lp}^{ui} z'_{pi} e_u]$ 确定;

在 $w_{lp}(i < l < p)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,
 $\frac{dw_{lp}}{d\theta}(0) = \sqrt{-1} \sum_s w_l Q_{li}^{(s)} e'_t z_{ip} (A_{li}^{sp})' + \sqrt{-1} \sum_{s,u} z_{li}^{(u)} u_p (Q_{ip}^{(s)})' e'_t e_s (A_{li}^{up})'$ 确定;

在 $w_{lp}(i < l < p)$ 的表达式中, 待定参数由初值 $w_{lp}(0) = z_{lp}$,
 $\frac{dw_{lp}}{d\theta}(0) = \sqrt{-1} \sum_s u_l (Q_{il}^{(s)})' e'_t z_{ip} A_{il}^{sp} + \sqrt{-1} \sum_{s,u} z_{il}^{(u)} u_p (Q_{ip}^{(s)})' e'_t e_s A_{il}^{up}$ 确定.

二 计算 $\tilde{Y}_i^{(t)} + P_i^{(t)}$, $i \in \{i_1, \dots, i_\rho\}$ 所决定的单参数子群 $\exp(\theta(\tilde{Y}_i^{(t)} + P_i^{(t)}))$.
 由引理 2.5 列出满足零点初值为 (z, u) 的常微分方程组

$$\frac{dr_i}{d\theta} = 2r_i v_i^{(t)} + 2\sqrt{-1} v_i^{(t)},$$

$$\frac{dr_p}{d\theta} = 2 \sum_s w_{pi}^{(s)} v_p Q_{pi}^{(s)} e'_t, \quad p < i,$$

$$\frac{dr_p}{d\theta} = 2 \sum_s w_{ip}^{(s)} v_p (Q_{ip}^{(s)})' e'_t, \quad p > i,$$

$$\frac{dv_i}{d\theta} = 2v_i^{(t)} v_i + \sqrt{-1} r_i e_t + e_t,$$

$$\frac{dv_p}{d\theta} = \sum_s [\sqrt{-1} w_{pi}^{(s)} e_t (Q_{pi}^{(s)})' + v_p Q_{pi}^{(s)} e'_t v_i (Q_{pi}^{(s)})'], \quad p < i,$$

$$\frac{dv_p}{d\theta} = \sum_s [\sqrt{-1} w_{ip}^{(s)} e_t Q_{ip}^{(s)} + v_p (Q_{ip}^{(s)})' e'_t v_i Q_{ip}^{(s)}], \quad p > i,$$

$$\frac{dw_{pi}}{d\theta} = \sum_s (r_i + \sqrt{-1}) v_p Q_{pi}^{(s)} e'_t e_s + \sum_{s,r} w_{pi}^{(s)} v_i (Q_{pi}^{(r)})' Q_{pi}^{(s)} e'_t e_r, \quad p < i,$$

$$\frac{dw_{ip}}{d\theta} = \sum_s (r_i + \sqrt{-1}) v_p (Q_{ip}^{(s)})' e'_t e_s + \sum_{s,r} w_{ip}^{(s)} v_i Q_{ip}^{(r)} (Q_{ip}^{(s)})' e'_t e_r, \quad p > i,$$

$$\frac{dw_{lp}}{d\theta} = \sum_{s,u} [v_p Q_{pi}^{(s)} e'_t w_{li} A_{lp}^{ui} e'_s e_u + v_l Q_{li}^{(s)} e'_t e_s A_{lp}^{ui} w_{pi} e_u], \quad l < p < i,$$

$$\frac{dw_{lp}}{d\theta} = \sum_s v_l Q_{li}^{(s)} e'_t w_{ip} (A_{li}^{sp})' + \sum_{s,u} w_{li}^{(u)} v_p (Q_{ip}^{(s)})' e'_t e_s (A_{li}^{up})', \quad l < i < p,$$

$$\frac{dw_{lp}}{d\theta} = \sum_s v_l (Q_{il}^{(s)})' e'_t w_{ip} A_{il}^{sp} + \sum_{s,u} w_{il}^{(u)} v_p (Q_{ip}^{(s)})' e'_t e_s A_{il}^{up}, \quad i < l < p.$$

同一中微分方程组的求解类似, 计算结果即 $\exp(\theta(\tilde{Y}_i^{(t)} + P_i^{(t)}))$ 的表达式见定理中 (3-ii).

$$\S 3.4 \quad \exp(t(B_i + \frac{\partial}{\partial s_i})), \quad \exp(\theta(T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}))$$

在这一节, 我们计算 $B_i + \frac{\partial}{\partial s_i}$, $T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}$ 所决定的单参数子群.

一 计算 $B_i + \frac{\partial}{\partial s_i}$, $i \in \{i_1, \dots, i_\rho\}$ 所决定的单参数子群 $\exp(t(B_i + \frac{\partial}{\partial s_i}))$.

由引理 2.5 列出满足零点初值为 (z, u) 的常微分方程组

$$\begin{aligned} \frac{dr_p}{dt} &= w_{pi} w'_{pi}, \quad p < i, \\ \frac{dr_p}{dt} &= w_{ip} w'_{ip}, \quad p > i, \\ \frac{dr_i}{dt} &= r_i^2 + 1, \\ \frac{dw_{pi}}{dt} &= r_i w_{pi}, \quad p < i, \\ \frac{dw_{ip}}{dt} &= r_i w_{ip}, \quad p > i, \\ \frac{dw_{kp}}{dt} &= \sum_s w_{ki} A_{kp}^{si} w'_{pi} e_s, \quad k < p < i, \\ \frac{dw_{kp}}{dt} &= \sum_s w_{ki}^{(s)} w_{ip} (A_{ki}^{sp})', \quad k < i < p, \\ \frac{dw_{kp}}{dt} &= \sum_s w_{ik}^{(s)} w_{ip} A_{ik}^{sp}, \quad i < k < p, \\ \frac{dv_p}{dt} &= \sum_s w_{pi}^{(s)} v_i \overline{Q_{pi}^{(s)}}', \quad p < i, \\ \frac{dv_i}{dt} &= r_i v_i, \\ \frac{dv_p}{dt} &= \sum_s w_{ip}^{(s)} v_i Q_{ip}^{(s)}, \quad p > i. \end{aligned}$$

下面求解这个常微分方程组.

(1) 求 r_i .

$$\text{由 } \begin{cases} \frac{dr_i}{dt} = r_i^2 + 1 \\ r_i(0) = s_i \end{cases} \text{ 得 } r_i = \operatorname{tg}(t + \operatorname{arctg} s_i).$$

(2) $v_i, w_{pi}(p < i), w_{ip}(p > i)$ 的求法相同, 这里只写出 v_i 的求法.

$$\text{由 } \begin{cases} \frac{dv_i}{dt} = r_i v_i = \operatorname{tg}(t + \operatorname{arctg} s_i) v_i \\ v_i(0) = u_i \end{cases} \text{ 得 } v_i = \sec(t + \operatorname{arctg} s_i) \frac{u_i}{\sqrt{1 + s_i^2}}.$$

(3) $r_p(p > i), r_p(p < i)$ 的求法相同, 这里只写出 $r_p(p > i)$ 的求法.

$$\text{由 } \begin{cases} \frac{dr_p}{dt} = w_{ip} w'_{ip} = \sec^2(t + \operatorname{arctg} s_i) \frac{1}{1 + s_i^2} z_{ip} z'_{ip} \\ r_p(0) = s_p \end{cases} \text{ 得}$$

$$r_p = s_p + \frac{\operatorname{tg}(t + \operatorname{arctg} s_i) - s_i}{1 + s_i^2} z_{ip} z'_{ip}.$$

(4) $w_{kp}(k < p < i)$, $w_{kp}(k < i < p)$, $w_{kp}(i < k < p)$ 的求法相同, 这里只写出 $w_{kp}(k < p < i)$ 的求法.

$$\text{由 } \begin{cases} \frac{dw_{kp}}{dt} = \sum_s w_{ki} A_{kp}^{si} w'_{pi} e_s = \sum_s \sec^2(t + \arctg s_i) \frac{1}{1+s_i^2} z_{ki} A_{kp}^{si} z'_{pi} e_s \\ w_{kp}(0) = z_{kp} \end{cases} \text{ 得;}$$

$$w_{kp} = z_{kp} + \sum_s \frac{\tg(t + \arctg s_i) - s_i}{1 + s_i^2} z_{ki} A_{kp}^{si} z'_{pi} e_s.$$

(5) $v_p(p < i)$, $v_p(p > i)$ 的求法相同, 这里只写出 $v_p(p < i)$ 的求法.

$$\text{由 } \begin{cases} \frac{dv_p}{dt} = \sum_s w_{pi}^{(s)} v_i(Q_{pi}^{(s)})' = \sum_s \sec^2(t + \arctg s_i) \frac{1}{1+s_i^2} z_{pi}^{(s)} u_i(Q_{pi}^{(s)})' \\ v_p(0) = u_p \end{cases} \text{ 得}$$

$$v_p = u_p + \sum_s \frac{\tg(t + \arctg s_i) - s_i}{1 + s_i^2} z_{pi}^{(s)} u_i(Q_{pi}^{(s)})',$$

引入新的参数 $\theta = \tg t$, 则 $t = 0$ 等价于 $\theta = 0$.

$$\tg(t + \arctg s_i) = \frac{\theta + s_i}{1 - s_i \theta}, \quad \sec(t + \arctg s_i) = \frac{\sqrt{(1 + s_i^2)(1 + \theta^2)}}{1 - s_i \theta}.$$

所以, $\exp(\arctg \theta(B_i + \frac{\theta}{\partial s_i}))$ 可以表示为:

$$r_i = \frac{s_i + \theta}{1 - s_i \theta},$$

$$r_p = s_p + \frac{\theta}{1 - s_i \theta} z_{pi} z'_{pi}, \quad p < i,$$

$$r_p = s_p + \frac{\theta}{1 - s_i \theta} z_{ip} z'_{ip}, \quad p > i,$$

$$w_{pi} = \frac{\sqrt{1 + \theta^2}}{1 - s_i \theta} z_{pi}, \quad p < i,$$

$$w_{ip} = \frac{\sqrt{1 + \theta^2}}{1 - s_i \theta} z_{ip}, \quad p > i,$$

$$w_{kp} = z_{kp} + \sum_s \frac{\theta}{1 - s_i \theta} z_{ki} A_{kp}^{si} z'_{pi} e_s, \quad k < p < i,$$

$$w_{kp} = z_{kp} + \sum_s \frac{\theta}{1 - s_i \theta} z_{ki}^{(s)} z_{ip} (A_{ki}^{sp})', \quad k < i < p,$$

$$w_{kp} = z_{kp} + \sum_s \frac{\theta}{1 - s_i \theta} z_{ik}^{(s)} z_{ip} A_{ik}^{sp}, \quad i < k < p,$$

$$v_i = \frac{\sqrt{1+\theta^2}}{1-s_i\theta} u_i,$$

$$v_p = u_p + \sum_s \frac{\theta}{1-s_i\theta} z_{pi}^{(s)} u_i \overline{(Q_{pi}^{(s)})'}, \quad p < i,$$

$$v_p = u_p + \sum_s \frac{\theta}{1-s_i\theta} z_{ip}^{(s)} u_i Q_{ip}^{(s)}, \quad p > i.$$

二 计算 $T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}$, $1 \leq t \leq n_{ij}$, $i < j$, $i, j \in \{i_1, \dots, i_\rho\}$ 所确定的单参数子群 $\exp(\theta(T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}))$.

由引理 2.5 列出满足零点初值为 (z, u) 的常微分方程组

$$\begin{aligned} \frac{dr_i}{d\theta} &= 2r_i w_{ij}^{(t)}, \\ \frac{dr_j}{d\theta} &= 2r_j w_{ij}^{(t)}, \\ \frac{dr_p}{d\theta} &= 2 \sum_s w_{pi}^{(s)} w_{pj} A_{pi}^{sj} e'_t, \quad p < i, \\ \frac{dr_p}{d\theta} &= 2 \sum_s w_{ip}^{(s)} e_t A_{ip}^{sj} w'_{pj}, \quad i < p < j, \\ \frac{dr_p}{d\theta} &= 2w_{ip} A_{ij}^{tp} w'_{jp}, \quad p > j, \\ \frac{dv_i}{d\theta} &= r_i v_j \overline{(Q_{ij}^{(t)})'} + \sum_s w_{ij}^{(s)} v_i Q_{ij}^{(t)} \overline{(Q_{ij}^{(s)})'}, \\ \frac{dv_j}{d\theta} &= r_j v_i Q_{ij}^{(t)} + \sum_s w_{ij}^{(s)} v_j \overline{(Q_{ij}^{(t)})'} Q_{ij}^{(s)}, \\ \frac{dv_p}{d\theta} &= \sum_s [w_{pj} A_{pi}^{sj} e'_t v_i \overline{(Q_{pi}^{(s)})'} + w_{pi}^{(s)} v_j \overline{(Q_{ij}^{(t)})'} \overline{(Q_{pi}^{(s)})'}], \quad p < i, \\ \frac{dv_p}{d\theta} &= \sum_s [e_t A_{ip}^{sj} w'_{pj} v_i Q_{ip}^{(s)} + w_{ip}^{(s)} v_j \overline{(Q_{ij}^{(t)})'} Q_{ip}^{(s)}], \quad i < p < j, \\ \frac{dv_p}{d\theta} &= \sum_s [w_{jp} (A_{ij}^{tp})' e'_s v_i Q_{ip}^{(s)} + w_{ip}^{(s)} v_j \overline{(Q_{ij}^{(t)})'} Q_{ip}^{(s)}], \quad p > j, \\ \frac{dw_{ij}}{d\theta} &= (r_i r_j - w_{ij} w'_{ij}) e_t + 2w_{ij}^{(t)} w_{ij} + 2e_t, \\ \frac{dw_{pi}}{d\theta} &= r_i \sum_s w_{pj} A_{pi}^{sj} e'_t e_s + \sum_{s,r} w_{pi}^{(s)} w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r, \quad p < i, \\ \frac{dw_{ip}}{d\theta} &= r_i \sum_s e_t A_{ip}^{sj} w'_{pj} e_s + \sum_{s,r} w_{ip}^{(s)} w_{ij} A_{ip}^{rj} (A_{ip}^{sj})' e'_t e_r, \quad i < p < j, \\ \frac{dw_{ip}}{d\theta} &= r_i w_{jp} (A_{ij}^{tp})' + \sum_s w_{ij}^{(s)} w_{ip} A_{ij}^{tp} (A_{ij}^{sp})', \quad p > j, \end{aligned}$$

$$\begin{aligned}
\frac{dw_{pj}}{d\theta} &= r_j \sum_s w_{pi}^{(s)} e_t (A_{pi}^{sj})' + \sum_s w_{pj} A_{pi}^{sj} e_t' w_{ij} (A_{pi}^{sj})', \quad p < i, \\
\frac{dw_{pj}}{d\theta} &= r_j \sum_s w_{ip}^{(s)} e_t A_{ip}^{sj} + \sum_s e_t A_{ip}^{sj} w_{pj}' w_{ij} A_{ip}^{sj}, \quad i < p < j, \\
\frac{dw_{jp}}{d\theta} &= r_j w_{ip} A_{ij}^{tp} + \sum_s w_{ij}^{(s)} w_{jp} (A_{ij}^{tp})' A_{ij}^{sp}, \quad p > j, \\
\frac{dw_{pk}}{d\theta} &= \sum_{s,r} [w_{pj} A_{pi}^{sj} e_t' e_s A_{pk}^{ri} w_{ki}' e_r + w_{kj} A_{ki}^{sj} e_t' e_s (A_{pk}^{ri})' w_{pi}' e_r], \quad p < k < i, \\
\frac{dw_{pk}}{d\theta} &= \sum_{s,r} w_{pi}^{(r)} e_t A_{ik}^{sj} w_{kj}' e_s (A_{pi}^{rk})' + \sum_s w_{pj} A_{pi}^{sj} e_t' w_{ik} (A_{pi}^{sk})', \quad p < i < k < j, \\
\frac{dw_{pk}}{d\theta} &= \sum_s [w_{pi}^{(s)} w_{jk} (A_{ij}^{tk})' (A_{pi}^{sk})' + w_{pj} A_{pi}^{sj} e_t' w_{ik} (A_{pi}^{sk})'], \quad p < i < j < k, \\
\frac{dw_{pk}}{d\theta} &= \sum_{s,r} w_{ip}^{(r)} e_t A_{ik}^{sj} w_{kj}' e_s A_{ip}^{rk} + \sum_s e_t A_{ip}^{sj} w_{pj}' w_{ik} A_{ip}^{sk}, \quad i < p < k < j, \\
\frac{dw_{pk}}{d\theta} &= \sum_s [w_{ip}^{(s)} w_{jk} (A_{ij}^{tk})' A_{ip}^{sk} + e_t A_{ip}^{sj} w_{pj}' w_{ik} A_{ip}^{sk}], \quad i < p < j < k, \\
\frac{dw_{pk}}{d\theta} &= \sum_s [w_{jp} (A_{ij}^{tp})' e_s' w_{ik} A_{ip}^{sk} + w_{ip}^{(s)} w_{jk} (A_{ij}^{tk})' A_{ip}^{sk}], \quad j < p < k.
\end{aligned}$$

下面求解这个常微分方程组.

(1) 求 r_i, r_j, w_{ij} .

首先计算 $w_{ij}^{(t)}$.

由

$$\frac{dw_{ij}}{d\theta} = (r_i r_j - w_{ij} w_{ij}') e_t + 2w_{ij}^{(t)} w_{ij} + 2e_t,$$

得

$$\begin{aligned}
\frac{dw_{ij}^{(t)}}{d\theta} &= r_i r_j - \sum_{s \neq t} w_{ij}^{(s)2} + w_{ij}^{(t)2} + 2, \\
\frac{d^2 w_{ij}^{(t)}}{d\theta^2} &= 4w_{ij}^{(t)} (r_i r_j - \sum_{s \neq t} w_{ij}^{(s)2}) + 2w_{ij}^{(t)} \frac{dw_{ij}^{(t)}}{d\theta} \\
&= 4w_{ij}^{(t)} \left(\frac{dw_{ij}^{(t)}}{d\theta} - w_{ij}^{(t)2} - 2 \right) + 2w_{ij}^{(t)} \frac{dw_{ij}^{(t)}}{d\theta} \\
&= 6w_{ij}^{(t)} \frac{dw_{ij}^{(t)}}{d\theta} - 4w_{ij}^{(t)3} - 8w_{ij}^{(t)}.
\end{aligned}$$

所以可列出满足初始条件的微分方程

$$\begin{cases} \frac{d^2 w_{ij}^{(t)}}{d\theta^2} = 6w_{ij}^{(t)} \frac{dw_{ij}^{(t)}}{d\theta} - 4w_{ij}^{(t)3} - 8w_{ij}^{(t)} \\ w_{ij}^{(t)}(0) = z_{ij}^{(t)} \\ \frac{dw_{ij}^{(t)}}{d\theta}(0) = s_i s_j - \sum_{s \neq t} z_{ij}^{(s)2} + z_{ij}^{(t)2} + 2 \end{cases}$$

令 $p = \frac{dw_{ij}^{(t)}}{d\theta}$, 则

$$\frac{d^2 w_{ij}^{(t)}}{d\theta^2} = p \frac{dp}{dw_{ij}^{(t)}} = 6w_{ij}^{(t)} p - 4w_{ij}^{(t)3} - 8w_{ij}^{(t)},$$

$$p dp = (3p - 2w_{ij}^{(t)2} - 4) dw_{ij}^{(t)2}.$$

令 $u = w_{ij}^{(t)2}$, 则

$$\frac{dp}{du} = \frac{3p - 2u - 4}{p},$$

令 $P = p, U = u + 2$, 则

$$\frac{dP}{dU} = 3 - 2\frac{U}{P},$$

令 $q = \frac{P}{U}$, 则

$$U \frac{dq}{dU} + q = 3 - \frac{2}{q},$$

所以

$$-\frac{1}{q-1} dq + \frac{2}{q-2} dq = -\frac{1}{U} dU,$$

即

$$-\frac{1}{1-q} d(1-q) + \frac{2}{q-2} d(q-2) = -\frac{1}{U} dU,$$

$$\frac{(q-2)^2}{1-q} = \frac{1}{cU},$$

$$q = \frac{4cU - 1 \pm \sqrt{1 - 4cU}}{2cU},$$

$$P = \frac{4cU - 1 \pm \sqrt{1 - 4cU}}{2c},$$

$$p = \frac{4c(u+2) - 1 \pm \sqrt{1 - 4c(u+2)}}{2c},$$

$$\frac{dw_{ij}^{(t)}}{d\theta} = \frac{4c(w_{ij}^{(t)2} + 2) - 1 \pm \sqrt{1 - 4c(w_{ij}^{(t)2} + 2)}}{2c} \quad (3.4.1).$$

不妨在此处取“+”号，因为从后面的计算可知，无论取“+”还是取“-”，最后所得的 $w_{ij}^{(t)}$ 都相同。

$$\frac{2cdw_{ij}^{(t)}}{4c(w_{ij}^{(t)})^2 + 2) - 1 + \sqrt{1 - 4c(w_{ij}^{(t)})^2 + 2}} = d\theta,$$

令

$$\frac{4c}{1 - 8c} w_{ij}^{(t)2} = \sin^2 \alpha,$$

$$\frac{\sqrt{c}d\alpha}{1 - \sqrt{1 - 8c} \cos \alpha} = d\theta,$$

令

$$t = \operatorname{tg} \frac{\alpha}{2},$$

$$\frac{2\sqrt{c}}{1 + t^2 - \sqrt{1 - 8c}(1 - t^2)} dt = d\theta,$$

所以

$$\frac{1}{\sqrt{2}} \operatorname{arctg} \frac{2\sqrt{2c}}{1 - \sqrt{1 - 8c}} t = \theta + c',$$

由 $\frac{4c}{1 - 8c} w_{ij}^{(t)2} = \sin^2 \alpha$ ，可得

$$w_{ij}^{(t)} = \sqrt{\frac{1 - 8c}{c}} \frac{t}{1 + t^2},$$

$$t = \frac{\sqrt{\frac{1 - 8c}{c}} + \sqrt{\frac{1 - 8c}{c} - 4w_{ij}^{(t)2}}}{2w_{ij}^{(t)}},$$

所以

$$\frac{\sqrt{1 - 8c} + \sqrt{1 - 8c - 4cw_{ij}^{(t)2}}}{w_{ij}^{(t)}} = \frac{1 - \sqrt{1 - 8c}}{\sqrt{2}} \operatorname{tg} \sqrt{2}(\theta + c'),$$

进一步写出 $w_{ij}^{(t)}$ 的显式表达式

$$\frac{\sqrt{\frac{1 - 8c}{c}} + \sqrt{\frac{1 - 8c}{c} - 4w_{ij}^{(t)2}}}{2w_{ij}^{(t)}} = \frac{1 - \sqrt{1 - 8c}}{2\sqrt{2c}} \operatorname{tg} \sqrt{2}(\theta + c'),$$

令

$$m = \sqrt{\frac{1 - 8c}{c}}, \quad A = \frac{1 - \sqrt{1 - 8c}}{2\sqrt{2c}},$$

$$\frac{m + \sqrt{m^2 - 4w_{ij}^{(t)2}}}{2w_{ij}^{(t)}} = A \operatorname{tg} \sqrt{2}(\theta + c'),$$

$$\sqrt{m^2 - 4w_{ij}^{(t)2}} = 2A \operatorname{tg} \sqrt{2}(\theta + c') w_{ij}^{(t)} - m,$$

令

$$\varphi = \theta + c'$$

所以

$$w_{ij}^{(t)} = \frac{mA \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \quad (3.4.2).$$

由 (3.4.1), (3.4.2) 式及初值条件可得:

$$c = \frac{\sum_{s \neq t} z_{ij}^{(s)2} - s_i s_j}{(s_i s_j - z_{ij} z_{ij}' - 2)^2}, \quad c' = \frac{1}{\sqrt{2}} \operatorname{arctg} \sqrt{2} \frac{\sqrt{1-8c} + \sqrt{1-8c-4cz_{ij}^{(t)2}}}{1 - \sqrt{1-8cz_{ij}^{(t)}}},$$

$r_i, r_j, w_{ij}^{(s)}$ ($s \neq t$) 的求法相同, 只写出 r_i 的求法.

$$\frac{dr_i}{d\theta} = 2r_i w_{ij}^{(t)},$$

令

$$x = A \operatorname{tg} \sqrt{2}(\theta + c'),$$

则

$$w_{ij}^{(t)} = \frac{mx}{1+x^2}, \quad \frac{dx}{d\theta} = \sqrt{2} \frac{x^2 + A^2}{A},$$

$$\frac{dr_i}{r_i} = 2w_{ij}^{(t)} d\theta = \frac{mA}{\sqrt{2}(A^2-1)} \left(\frac{1}{1+x^2} - \frac{1}{A^2+x^2} \right) dx^2 = \left(\frac{1}{A^2+x^2} - \frac{1}{1+x^2} \right) dx^2,$$

$$d \ln r_i = d \ln \frac{A^2+x^2}{1+x^2},$$

所以

$$r_i = c_1 \frac{A^2+x^2}{1+x^2}$$

由初值条件 $r_i(0) = s_i$ 及 $x = A \operatorname{tg} \sqrt{2}(\theta + c')$ 可得

$$c_1 = s_i \frac{1 + (A \operatorname{tg} \sqrt{2}c')^2}{A^2 + (A \operatorname{tg} \sqrt{2}c')^2} = s_i \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{A^2},$$

所以

$$r_i = s_i \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}.$$

在验证解的过程中,可以得到一个重要的关系式:

$$mA = \sqrt{2}(1 - A^2).$$

(2) $w_{pi}(p < i)$, $w_{pj}(p < i)$, $w_{ip}(i < p < j)$, $w_{pj}(i < p < j)$, $w_{ip}(p > j)$, $w_{jp}(p > j)$, v_i, v_j 的求法相同. 下面只写出 $w_{pi}(p < i)$ 的求法.

由

$$\frac{dw_{pi}}{d\theta} = r_i \sum_s w_{pj} A_{pi}^{sj} e'_t e_s + \sum_{s,r} w_{pi}^{(s)} w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r,$$

得

$$\begin{aligned} \frac{d^2 w_{pi}}{d\theta^2} &= \frac{dr_i}{d\theta} \sum_s w_{pj} A_{pi}^{sj} e'_t e_s + r_i \sum_s \frac{dw_{pj}}{d\theta} A_{pi}^{sj} e'_t e_s \\ &\quad + \sum_{s,r} \frac{dw_{pi}^{(s)}}{d\theta} w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r + \sum_{s,r} w_{pi}^{(s)} \frac{dw_{ij}}{d\theta} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r \\ &= 2r_i w_{ij}^{(t)} \sum_s w_{pj} A_{pi}^{sj} e'_t e_s + r_i r_j \sum_{s,u} w_{pi}^{(u)} e_t (A_{pi}^{uj})' A_{pi}^{sj} e'_t e_s + r_i \sum_{s,u} w_{pj} A_{pi}^{uj} e'_t w_{ij} (A_{pi}^{sj})' A_{pi}^{sj} e'_t e_s \\ &\quad + r_i \sum_{s,r} w_{pj} A_{pi}^{sj} e'_t w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r + \sum_{s,r,u} w_{pi}^{(s)} w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t w_{ij} (A_{pi}^{uj})' A_{pi}^{rj} e'_t e_u \\ &\quad + 2w_{ij}^{(t)} \sum_{s,r} w_{pi}^{(s)} w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r + \sum_{s,r} w_{pi}^{(s)} (r_i r_j - w_{ij} w'_{ij} + 2) e_t (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r \\ &= 4w_{ij}^{(t)} r_i \sum_s w_{pj} A_{pi}^{sj} e'_t e_s - r_i \sum_{s,u} w_{pj} A_{pi}^{uj} e'_t w_{ij} (A_{pi}^{sj})' A_{pi}^{uj} e'_t e_s \\ &\quad + r_i \sum_{s,r} w_{pj} A_{pi}^{sj} e'_t w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r - \sum_{s,r,u} w_{pi}^{(s)} w_{ij} (A_{pi}^{sj})' A_{pi}^{rj} e'_t e_t (A_{pi}^{rj})' A_{pi}^{uj} w_{ij}' e_u \\ &\quad + 2w_{ij}^{(t)} \sum_{s,u} w_{pi}^{(s)} w_{ij} (A_{pi}^{uj})' A_{pi}^{sj} e'_t e_u + 2w_{ij}^{(t)} \sum_{s,r} w_{pi}^{(s)} w_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r \\ &\quad + 2r_i r_j w_{pi} + (-w_{ij} w'_{ij} + 2) w_{pi} \\ &= 4w_{ij}^{(t)} \frac{dw_{pi}}{d\theta} + 2(r_i r_j - w_{ij} w'_{ij} + 1) w_{pi} \end{aligned}$$

以上计算利用了公式

$$\begin{aligned} e_t (A_{pi}^{rj})' A_{pi}^{sj} e'_t &= \delta_{s,r}; \\ \sum_u A_{pi}^{uj} e'_t e_t (A_{pi}^{uj})' &= I; \\ (A_{pi}^{uj})' A_{pi}^{sj} + (A_{pi}^{sj})' A_{pi}^{uj} &= 2\delta_{s,u} I^{(n_{ij})}. \end{aligned}$$

下面求解二阶微分方程:

$$\frac{d^2 w_{pi}}{d\theta^2} = 4w_{ij}^{(t)} \frac{dw_{pi}}{d\theta} + 2(r_i r_j - w_{ij} w'_{ij} + 1) w_{pi}.$$

由 $w_{ij}^{(t)} = \frac{mx}{1+x^2}$, $x = Atg\sqrt{2}(\theta + c')$, $mA = \sqrt{2}(1 - A^2)$, 及

$$\frac{dw_{ij}^{(t)}}{d\theta} = (r_i r_j - w_{ij} w'_{ij} + 2) + 2w_{ij}^{(t)2},$$

可得

$$\begin{aligned} r_i r_j - w_{ij} w'_{ij} + 1 &= \frac{dw_{ij}^{(t)}}{d\theta} - 2w_{ij}^{(t)2} - 1 \\ &= m \frac{1-x^2}{(1+x^2)^2} \frac{\sqrt{2}(A^2+x^2)}{A} - 2 \frac{m^2 x^2}{(1+x^2)^2} - 1 \\ &= \sqrt{2}(1-A^2) \frac{1-x^2}{(1+x^2)^2} \frac{\sqrt{2}(A^2+x^2)}{A^2} - 2 \frac{2(1-A^2)^2}{A^2} \frac{x^2}{(1+x^2)^2} - 1 \\ &= \frac{A^2 - 2A^4 + (A^2 - 2)x^2}{A^2(1+x^2)} \end{aligned}$$

所以

$$\frac{d^2 w_{pi}}{d\theta^2} = 4 \frac{\sqrt{2}(1-A^2)x}{A(1+x^2)} \frac{dw_{pi}}{d\theta} + 2 \frac{A^2 - 2A^4 + (A^2 - 2)x^2}{A^2(1+x^2)} w_{pi}.$$

令

$$\varphi = \theta + c',$$

$$\begin{aligned} \frac{d^2 w_{pi}}{d\varphi^2} &= \frac{4\sqrt{2}(1-A^2)tg\sqrt{2}\varphi}{1+A^2tg^2\sqrt{2}\varphi} \frac{dw_{pi}}{d\varphi} + 2 \frac{A^2 - 2A^4 + (A^2 - 2)A^2tg^2\sqrt{2}\varphi}{A^2(1+A^2tg^2\sqrt{2}\varphi)} w_{pi}, \\ &= \frac{4\sqrt{2}(1-A^2)\sin\sqrt{2}\varphi\cos\sqrt{2}\varphi}{\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi} \frac{dw_{pi}}{d\varphi} \\ &\quad + 2 \frac{(A^2 - 2A^4)\cos^2\sqrt{2}\varphi + (A^2 - 2)A^2\sin^2\sqrt{2}\varphi}{A^2(\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi)} w_{pi}, \end{aligned}$$

$$\begin{aligned} &(\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi) \frac{d^2 w_{pi}}{d\varphi^2} \\ &= 4\sqrt{2}(1-A^2)\sin\sqrt{2}\varphi\cos\sqrt{2}\varphi \frac{dw_{pi}}{d\varphi} + [2(1-2A^2)\cos^2\sqrt{2}\varphi + 2(A^2-2)\sin^2\sqrt{2}\varphi] w_{pi}, \\ &((\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi) \frac{dw_{pi}}{d\varphi})' \\ &= (2\sqrt{2}(1-A^2)\sin\sqrt{2}\varphi\cos\sqrt{2}\varphi w_{pi})' - 2(\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi) w_{pi}, \\ &((\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi) w_{pi})'' = -2(\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi) w_{pi}. \end{aligned}$$

而 $y'' = -2y$ 的解为: $y = d \sin \sqrt{2}(\varphi + d')$, d, d' 为待定参数.

所以

$$(\cos^2\sqrt{2}\varphi + A^2\sin^2\sqrt{2}\varphi) w_{pi}^{(u)} = d_{pi}^{(u)} \sin \sqrt{2}(\varphi + d_{pi}^{(u)'}),$$

$$w_{pi}^{(u)}(\varphi) = \frac{d_{pi}^{(u)} \sin \sqrt{2}(\varphi + d_{pi}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pi}.$$

下面利用初值条件确定 $d_{pi}^{(u)}$ 和 $d_{pi}^{(u)'}$.

$$\frac{dw_{pi}^{(u)}}{d\varphi} = \frac{\sqrt{2}d_{pi}^{(u)} \cos \sqrt{2}(\varphi + d_{pi}^{(u)'}) (\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi) + \sqrt{2}d_{pi}^{(u)} (1-A^2) \sin 2\sqrt{2}\varphi \sin \sqrt{2}(\varphi + d_{pi}^{(u)'})}{(\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi)^2}.$$

初值条件转化为:

$$\begin{cases} w_{pi}^{(u)}(c') = \frac{d_{pi}^{(u)} \sin \sqrt{2}(c' + d_{pi}^{(u)'})}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} = z_{pi}^{(u)} \\ \frac{dw_{pi}^{(u)}}{d\varphi}(c') \\ = \frac{\sqrt{2}d_{pi}^{(u)} \cos \sqrt{2}(c' + d_{pi}^{(u)'}) (\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c') + \sqrt{2}d_{pi}^{(u)} (1-A^2) \sin 2\sqrt{2}c' \sin \sqrt{2}(c' + d_{pi}^{(u)'})}{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2} \\ = [s_i \sum_s z_{pj} A_{pi}^{sj} e'_t e_s + \sum_{s,r} z_{pi}^{(s)} z_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r] e'_u \end{cases}$$

令 $D_{pi}^{(u)} = w_{pi}^{(u)}|_{\varphi=c'}$, $T_{pi}^{(u)} = \frac{dw_{pi}^{(u)}}{d\varphi}|_{\varphi=c'}$, 可得

$$d_{pi}^{(u)' } = \text{arctg} \left(\frac{T_{pi}^{(u)}}{\sqrt{2}D_{pi}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c',$$

$$d_{pi}^{(u)} = \frac{D_{pi}^{(u)} (\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')}{\sin \sqrt{2}(c' + d_{pi}^{(u)'})}.$$

所以

$$w_{pi}^{(u)}(\varphi) = z_{pi}^{(u)} \frac{\sin \sqrt{2}(\varphi + d_{pi}^{(u)'}) \cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{pi}^{(u)'}) \cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pi},$$

其中

$$d_{pi}^{(u)' } = \text{arctg} \left(\frac{[s_i \sum_s z_{pj} A_{pi}^{sj} e'_t e_s + \sum_{s,r} z_{pi}^{(s)} z_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e'_t e_r] e'_u}{\sqrt{2}z_{pi}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c'.$$

(3) $r_p(p < i)$, $r_p(i < p < j)$, $r_p(p > j)$, $w_{pk}(p < k < i)$, $w_{pk}(p < i < k < j)$, $w_{pk}(p < i < j < k)$, $w_{pk}(i < p < k < j)$, $w_{pk}(i < p < j < k)$, $w_{pk}(j < p < k)$, $v_p(p < i)$, $v_p(i < p < j)$, $v_p(p > j)$ 的求法相同. 下面只写出 $r_p(p < i)$ 的求法.

$$\frac{dr_p}{d\theta} = 2 \sum_s w_{pi}^{(s)} w_{pj} A_{pi}^{sj} e'_t,$$

将已求得的 $w_{pi}^{(s)}, w_{pj}$ 代入得

$$\begin{aligned} \frac{dr_p}{d\varphi} &= 2 \sum_{s,r} \frac{d_{pi}^{(s)} d_{pj}^{(r)} \sin \sqrt{2}(\varphi + d_{pi}^{(s)'}) \sin \sqrt{2}(\varphi + d_{pj}^{(r)'})}{(\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi)^2} e_r A_{pi}^{(sj)} e_t', \\ &\sin \sqrt{2}(\varphi + d_{pi}^{(s)'}) \sin \sqrt{2}(\varphi + d_{pj}^{(r)'}) \\ &= \sin^2 \sqrt{2}\varphi \cos \sqrt{2}d_{pi}^{(s)'} \cos \sqrt{2}d_{pj}^{(r)'} + \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi \cos \sqrt{2}d_{pi}^{(s)'} \sin \sqrt{2}d_{pj}^{(r)'} \\ &\quad + \cos \sqrt{2}\varphi \sin \sqrt{2}\varphi \sin \sqrt{2}d_{pi}^{(s)'} \cos \sqrt{2}d_{pj}^{(r)'} + \cos^2 \sqrt{2}\varphi \sin \sqrt{2}d_{pi}^{(s)'} \sin \sqrt{2}d_{pj}^{(r)'} \end{aligned}$$

微分方程的求解转化为求下面的 3 个不定积分:

$$\begin{aligned} \text{(I)} \quad &\int \frac{\sin^2 \sqrt{2}\varphi}{(\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi)^2} d\varphi, \\ \text{(II)} \quad &\int \frac{\sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{(\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi)^2} d\varphi, \\ \text{(III)} \quad &\int \frac{\cos^2 \sqrt{2}\varphi}{(\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi)^2} d\varphi. \end{aligned}$$

令 $t = tg\sqrt{2}\varphi$, 可得

$$\begin{aligned} \text{(I)} &= \frac{1}{2\sqrt{2}A^3} \left(\text{arctg } At - \frac{At}{1 + A^2 t^2} \right) + C, \\ \text{(II)} &= \frac{1}{2\sqrt{2}(1 - A^2)} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + C, \\ \text{(III)} &= \frac{1}{2\sqrt{2}A} \left(\text{arctg } At + \frac{At}{1 + A^2 t^2} \right) + C. \end{aligned}$$

所以

$$\begin{aligned} r_p(\varphi) &= \frac{1}{\sqrt{2}} \sum_{s,r} \left[\frac{1}{A^3} \left(\text{arctg } Atg\sqrt{2}\varphi - \frac{Atg\sqrt{2}\varphi}{1 + A^2 tg^2 \sqrt{2}\varphi} \right) \cos \sqrt{2}d_{pi}^{(s)'} \cos \sqrt{2}d_{pj}^{(r)'} \right. \\ &\quad + \frac{1}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \sin \sqrt{2}(d_{pi}^{(s)'} + d_{pj}^{(r)'}) \\ &\quad \left. + \frac{1}{A} \left(\text{arctg } Atg\sqrt{2}\varphi + \frac{Atg\sqrt{2}\varphi}{1 + A^2 tg^2 \sqrt{2}\varphi} \right) \sin \sqrt{2}d_{pi}^{(s)'} \sin \sqrt{2}d_{pj}^{(r)'} \right] d_{pi}^{(s)} d_{pj}^{(r)} e_r A_{pi}^{sj} e_t' + a_0 \end{aligned}$$

由 $r_p(c') = s_p$, 可求出 a_0 .

综上, $\exp(\theta(T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}))$ 可表示为:

$$r_i = s_i \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi},$$

$$r_j = s_j \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi},$$

$$w_{ij} = w_{ij}^{(t)} e_t + \sum_{s \neq t} w_{ij}^{(s)} e_s = \frac{\sqrt{2}(1-A^2) \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \sum_{s \neq t} z_{ij}^{(s)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}$$

$$w_{pi}^{(u)} = z_{pi}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{pi}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{pi}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pi}, \quad p < i,$$

$$w_{pj}^{(u)} = z_{pj}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{pj}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{pj}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pj}, \quad p < i,$$

$$w_{ip}^{(u)} = z_{ip}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{ip}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{ip}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{ip}, \quad i < p < j,$$

$$w_{pj}^{(u)} = z_{pj}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{pj}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{pj}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{pj}, \quad i < p < j,$$

$$w_{ip}^{(u)} = z_{ip}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{ip}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{ip}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{ip}, \quad p > j,$$

$$w_{jp}^{(u)} = z_{jp}^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_{jp}^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_{jp}^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, n_{jp}, \quad p > j,$$

$$v_i^{(u)} = d_i^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_i^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_i^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, m_i,$$

$$v_j^{(u)} = d_j^{(u)} \frac{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'}{\sin \sqrt{2}(c' + d_j^{(u)'})} \frac{\sin \sqrt{2}(\varphi + d_j^{(u)'})}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}, \quad u = 1, \dots, m_j,$$

$$r_p = g_0(\varphi) + a_0, \quad p < i,$$

$$r_p = g_1(\varphi) + a_1, \quad i < p < j,$$

$$r_p = g_2(\varphi) + a_2, \quad p > j,$$

$$w_{pk} = g_3(\varphi) + a_3, \quad p < k < i,$$

$$w_{pk} = g_4(\varphi) + a_4, \quad p < i < k < j,$$

$$w_{pk} = g_5(\varphi) + a_5, \quad p < i < j < k,$$

$$w_{pk} = g_6(\varphi) + a_6, \quad i < p < k < j,$$

$$w_{pk} = g_7(\varphi) + a_7, \quad i < p < j < k,$$

$$\begin{aligned}
w_{pk} &= g_8(\varphi) + a_8, \quad j < p < k, \\
v_p &= g_9(\varphi) + a_9, \quad p < i, \\
v_p &= g_{10}(\varphi) + a_{10}, \quad i < p < j, \\
v_p &= g_{11}(\varphi) + a_{11}, \quad p > j.
\end{aligned}$$

其中

$$\begin{aligned}
c &= \frac{\sum_{s \neq t} z_{ij}^{(s)2} - s_i s_j}{(s_i s_j - z_{ij} z_{ij}' - 2)^2}, \\
c' &= \frac{1}{\sqrt{2}} \operatorname{arctg} \sqrt{2} \frac{\sqrt{1-8c} + \sqrt{1-8c-4cz_{ij}^{(t)2}}}{1 - \sqrt{1-8cz_{ij}^{(t)}}}, \quad A = \frac{1 - \sqrt{1-8c}}{2\sqrt{2c}}, \\
\varphi &= \theta + c',
\end{aligned}$$

在 $w_{pi}^{(u)}$ ($p < i$) 的表达式中,

$$d_{pi}^{(u)'} = \operatorname{arctg} \left(\frac{[s_i \sum_s z_{pj} A_{pi}^{sj} e_t' e_s + \sum_{s,r} z_{pi}^{(s)} z_{ij} (A_{pi}^{rj})' A_{pi}^{sj} e_t' e_r] e_u'}{\sqrt{2} z_{pi}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{pj}^{(u)}$ ($p < i$) 的表达式中,

$$d_{pj}^{(u)'} = \operatorname{arctg} \left(\frac{[s_j \sum_s z_{pi}^{(s)} e_t (A_{pi}^{sj})' + \sum_s z_{pj} A_{pi}^{sj} e_t' z_{ij} (A_{pi}^{sj})'] e_u'}{\sqrt{2} z_{pj}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{ip}^{(u)}$ ($i < p < j$) 的表达式中,

$$d_{ip}^{(u)'} = \operatorname{arctg} \left(\frac{[s_i \sum_s e_t A_{ip}^{sj} z_{pj}' e_s + \sum_{s,r} z_{ip}^{(s)} z_{ij} A_{ip}^{rj} (A_{ip}^{sj})' e_t' e_r] e_u'}{\sqrt{2} z_{ip}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{pj}^{(u)}$ ($i < p < j$) 的表达式中,

$$d_{pj}^{(u)'} = \operatorname{arctg} \left(\frac{[s_j \sum_s z_{ip}^{(s)} e_t A_{ip}^{sj} + \sum_s e_t A_{ip}^{sj} z_{pj}' z_{ij} A_{ip}^{sj}] e_u'}{\sqrt{2} z_{pj}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{ip}^{(u)}$ ($p > j$) 的表达式中,

$$d_{ip}^{(u)'} = \operatorname{arctg} \left(\frac{[s_i z_{jp} (A_{ij}^{tp})' + \sum_s z_{ij}^{(s)} z_{ip} A_{ij}^{tp} (A_{ij}^{sp})'] e_u'}{\sqrt{2} z_{ip}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $w_{jp}^{(u)}$ ($p > j$) 的表达式中,

$$d_{jp}^{(u)'} = \operatorname{arctg} \left(\frac{[s_j z_{ip} A_{ij}^{tp} + \sum_s z_{ij}^{(s)} z_{jp} (A_{ij}^{tp})' A_{ij}^{sp}] e_u'}{\sqrt{2} z_{jp}^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $v_i^{(u)}$ 的表达式中,

$$d_i^{(u)'} = \operatorname{arccctg} \left(\frac{[s_i u_j (Q_{ij}^{(t)})' + \sum_s z_{ij}^{(s)} u_i Q_{ij}^{(t)} (Q_{ij}^{(s)})'] e_u'}{\sqrt{2} u_i^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $v_j^{(u)}$ 的表达式中,

$$d_j^{(u)'} = \operatorname{arccctg} \left(\frac{[s_j u_i Q_{ij}^{(t)} + \sum_s z_{ij}^{(s)} u_j (Q_{ij}^{(t)})' Q_{ij}^{(s)}] e_u'}{\sqrt{2} u_j^{(u)}} - \frac{(1-A^2) \sin 2\sqrt{2}c'}{\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c'} \right) - c';$$

在 $r_p (p < i)$ 的表达式中,

$$\begin{aligned} g_0(\varphi) = & \frac{1}{\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{pi}^{(s)'} \cos \sqrt{2}d_{pj}^{(r)'}}{A^3} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pi}^{(s)'} + d_{pj}^{(r)'})}{1-A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(s)'} \sin \sqrt{2}d_{pj}^{(r)'}}{A} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \\ & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right] z_{pi}^{(s)} z_{pj}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(s)'}) \sin \sqrt{2}(c' + d_{pj}^{(r)'})} e_r A_{pi}^{sj} e_t', \end{aligned}$$

$$a_0 = s_p - g_0(c');$$

在 $r_p (i < p < j)$ 的表达式中,

$$\begin{aligned} g_1(\varphi) = & \frac{1}{\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{pj}^{(r)'}}{A^3} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{pj}^{(r)'})}{1-A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{pj}^{(r)'}}{A} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \\ & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right] z_{ip}^{(s)} z_{pj}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{pj}^{(r)'})} e_r (A_{ip}^{sj})' e_t', \end{aligned}$$

$$a_1 = s_p - g_1(c');$$

在 $r_p (p > j)$ 的表达式中,

$$\begin{aligned} g_2(\varphi) = & \frac{1}{\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{jp}^{(r)'}}{A^3} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{jp}^{(r)'})}{1-A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{jp}^{(r)'}}{A} (\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \\ & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right] z_{ip}^{(s)} z_{jp}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{jp}^{(r)'})} e_s A_{ij}^{tp} e_r', \end{aligned}$$

$$a_2 = s_p - g_2(c');$$

在 $w_{pk}(p < k < i)$ 的表达式中,

$$\begin{aligned}
g_3(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u,v} \left[\frac{\cos \sqrt{2}d_{pj}^{(u)'} \cos \sqrt{2}d_{ki}^{(v)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(u)'} + d_{ki}^{(v)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \\
& + \left. \frac{\sin \sqrt{2}d_{pj}^{(u)'} \sin \sqrt{2}d_{ki}^{(v)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right] \\
& z_{pj}^{(u)} z_{ki}^{(v)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(u)'}) \sin \sqrt{2}(c' + d_{ki}^{(v)'})} e_u A_{pi}^{sj} e_t' e_s A_{pk}^{ri} e_v' e_r \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r,u,v} \left[\frac{\cos \sqrt{2}d_{kj}^{(u)'} \cos \sqrt{2}d_{pi}^{(v)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{kj}^{(u)'} + d_{pi}^{(v)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \\
& + \left. \frac{\sin \sqrt{2}d_{kj}^{(u)'} \sin \sqrt{2}d_{pi}^{(v)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right] \\
& z_{kj}^{(u)} z_{pi}^{(v)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{kj}^{(u)'}) \sin \sqrt{2}(c' + d_{pi}^{(v)'})} e_u A_{ki}^{sj} e_t' e_s (A_{pk}^{ri})' e_v' e_r,
\end{aligned}$$

$$a_3 = z_{pk} - g_3(c');$$

在 $w_{pk}(p < i < k < j)$ 的表达式中,

$$\begin{aligned}
g_4(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pi}^{(r)'} \cos \sqrt{2}d_{kj}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pi}^{(r)'} + d_{kj}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(r)'} \sin \sqrt{2}d_{kj}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pi}^{(r)} z_{kj}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(r)'}) \sin \sqrt{2}(c' + d_{kj}^{(u)'})} e_t A_{ik}^{sj} e_u' e_s (A_{pi}^{rk})' \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_{ik}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi
\end{aligned}$$

$$+ \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_r A_{pi}^{sj} e'_t e_u (A_{pi}^{sk})',$$

$$a_4 = z_{pk} - g_4(c');$$

在 $w_{pk}(p < i < j < k)$ 的表达式中,

$$\begin{aligned} g_5(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{pi}^{(s)'}}{A^3} \cos \sqrt{2}d_{jk}^{(r)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pi}^{(s)'}) + d_{jk}^{(r)'}}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(s)'}}{A} \frac{\sin \sqrt{2}d_{jk}^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pi}^{(s)} z_{jk}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(s)'}) \sin \sqrt{2}(c' + d_{jk}^{(r)'})} e_r (A_{ij}^{tk})' (A_{pi}^{sk})' \\ & + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'}}{A^3} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pj}^{(r)'}) + d_{ik}^{(u)'}}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'}}{A} \frac{\sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_r A_{pi}^{sj} e'_t e_u (A_{pi}^{sk})', \end{aligned}$$

$$a_5 = z_{pk} - g_5(c');$$

在 $w_{pk}(i < p < k < j)$ 的表达式中,

$$\begin{aligned} g_6(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{ip}^{(r)'}}{A^3} \cos \sqrt{2}d_{kj}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{ip}^{(r)'}) + d_{kj}^{(u)'}}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(r)'}}{A} \frac{\sin \sqrt{2}d_{kj}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{ip}^{(r)} z_{kj}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(r)'}) \sin \sqrt{2}(c' + d_{kj}^{(u)'})} e_t A_{ik}^{sj} e'_u e_s A_{ip}^{rk} \\ & + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'}}{A^3} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\ & + \frac{\sin \sqrt{2}(d_{pj}^{(r)'}) + d_{ik}^{(u)'}}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'}}{A} \frac{\sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\ & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \Big] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_t A_{ip}^{sj} e'_r e_u A_{ip}^{sk}, \end{aligned}$$

$$a_6 = z_{pk} - g_6(c');$$

在 $w_{pk}(i < p < j < k)$ 的表达式中,

$$\begin{aligned}
 g_7(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{jk}^{(r)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
 & + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{jk}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{jk}^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
 & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{ip}^{(s)} z_{jk}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{jk}^{(r)'})} e_r (A_{ij}^{tk})' A_{ip}^{sk} \\
 & + \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
 & + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_{ik}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
 & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pj}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_t A_{ip}^{sj} e_r' e_u A_{ip}^{sk},
 \end{aligned}$$

$$a_7 = z_{pk} - g_7(c');$$

在 $w_{pk}(j < p < k)$ 的表达式中,

$$\begin{aligned}
 g_8(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{jp}^{(r)'} \cos \sqrt{2}d_{ik}^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
 & + \frac{\sin \sqrt{2}(d_{jp}^{(r)'} + d_{ik}^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{jp}^{(r)'} \sin \sqrt{2}d_{ik}^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
 & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{jp}^{(r)} z_{ik}^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{jp}^{(r)'}) \sin \sqrt{2}(c' + d_{ik}^{(u)'})} e_r (A_{ij}^{tp})' e_s' e_u A_{ip}^{sk} \\
 & + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_{jk}^{(r)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
 & + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_{jk}^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_{jk}^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
 & + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{ip}^{(s)} z_{jk}^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_{jk}^{(r)'})} e_r (A_{ij}^{tk})' A_{ip}^{sk},
 \end{aligned}$$

$$a_8 = z_{pk} - g_8(c');$$

在 $v_p(p < i)$ 的表达式中,

$$\begin{aligned}
g_9(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_i^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_i^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_i^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pj}^{(r)'} u_i^{(u)'} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_i^{(u)'})} e_r A_{pi}^{sj} e_t' e_u \overline{(Q_{pi}^{(s)})'} \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{pi}^{(s)'} \cos \sqrt{2}d_j^{(r)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pi}^{(s)'} + d_j^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pi}^{(s)'} \sin \sqrt{2}d_j^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pi}^{(s)'} u_j^{(r)'} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pi}^{(s)'}) \sin \sqrt{2}(c' + d_j^{(r)'})} e_r \overline{(Q_{ij}^{(t)})'} \overline{(Q_{pi}^{(s)})'},
\end{aligned}$$

$$a_9 = u_p - g_9(c');$$

在 $v_p(i < p < j)$ 的表达式中,

$$\begin{aligned}
g_{10}(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{pj}^{(r)'} \cos \sqrt{2}d_i^{(u)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{pj}^{(r)'} + d_i^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{pj}^{(r)'} \sin \sqrt{2}d_i^{(u)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{pj}^{(r)'} u_i^{(u)'} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{pj}^{(r)'}) \sin \sqrt{2}(c' + d_i^{(u)'})} e_t A_{ip}^{sj} e_r' e_u Q_{ip}^{(s)} \\
& + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_j^{(r)'}}{A^3} (\arctg \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \right. \\
& + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_j^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_j^{(r)'}}{A} (\arctg \operatorname{Atg} \sqrt{2}\varphi \\
& + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi}) \left. \right] z_{ip}^{(s)'} u_j^{(r)'} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_j^{(r)'})} e_r \overline{(Q_{ij}^{(t)})'} Q_{ip}^{(s)},
\end{aligned}$$

$$a_{10} = u_p - g_{10}(c');$$

在 $u_p (p > j)$ 的表达式中,

$$\begin{aligned}
 g_{11}(\varphi) = & \frac{1}{2\sqrt{2}} \sum_{s,r,u} \left[\frac{\cos \sqrt{2}d_{jp}^{(r)'} \cos \sqrt{2}d_i^{(u)'}}{A^3} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
 & + \frac{\sin \sqrt{2}(d_{jp}^{(r)'} + d_i^{(u)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{jp}^{(r)'} \sin \sqrt{2}d_i^{(u)'}}{A} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \right. \\
 & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \Big] z_{jp}^{(r)} u_i^{(u)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{jp}^{(r)'}) \sin \sqrt{2}(c' + d_i^{(u)'})} e_r (A_{ij}^{tp})' e'_s e_u Q_{ip}^{(s)} \\
 & + \frac{1}{2\sqrt{2}} \sum_{s,r} \left[\frac{\cos \sqrt{2}d_{ip}^{(s)'} \cos \sqrt{2}d_j^{(r)'}}{A^3} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi - \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \right. \\
 & + \frac{\sin \sqrt{2}(d_{ip}^{(s)'} + d_j^{(r)'})}{1 - A^2} \frac{1}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} + \frac{\sin \sqrt{2}d_{ip}^{(s)'} \sin \sqrt{2}d_j^{(r)'}}{A} \left(\operatorname{arctg} \operatorname{Atg} \sqrt{2}\varphi \right. \\
 & \left. + \frac{A \sin \sqrt{2}\varphi \cos \sqrt{2}\varphi}{\cos^2 \sqrt{2}\varphi + A^2 \sin^2 \sqrt{2}\varphi} \right) \Big] z_{ip}^{(s)} u_j^{(r)} \frac{(\cos^2 \sqrt{2}c' + A^2 \sin^2 \sqrt{2}c')^2}{\sin \sqrt{2}(c' + d_{ip}^{(s)'}) \sin \sqrt{2}(c' + d_j^{(r)'})} e_r (Q_{ij}^{(t)})' Q_{ip}^{(s)}.
 \end{aligned}$$

$$g_{11} = u_p - g_{11}(c').$$

正规 Siegel 域 $D(v_N, F)$ 中固定点 p 的迷向子群 $\operatorname{Iso}(D(v_N, F))$ 由 $\exp(o(D(v_N, F)))$, $\exp(\tilde{y}(D(v_N, F)))$, $\exp(\tilde{L}_1)$, $\exp(\tilde{L}_2)$ 生成. 而 $\tilde{y}(D(v_N, F))$ 以 $X_{ij}^{(t)} - Z_{ij}^{(t)}$ 为基, \tilde{L}_1 以 $Y_i^{(t)} - \tilde{P}_i^{(t)}$, $\tilde{Y}_i^{(t)} + P_i^{(t)}$ 为基, \tilde{L}_2 以 $B_i + \frac{\partial}{\partial s_i}$, $T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}$ 为基. 又 $X_{ij}^{(t)} - Z_{ij}^{(t)}$, $Y_i^{(t)} - \tilde{P}_i^{(t)}$, $\tilde{Y}_i^{(t)} + P_i^{(t)}$, $B_i + \frac{\partial}{\partial s_i}$, $T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}$ 所决定的单参数子群分别为 $\exp(\theta(X_{ij}^{(t)} - Z_{ij}^{(t)}))$, $\exp(\theta(Y_i^{(t)} - \tilde{P}_i^{(t)}))$, $\exp(\theta(\tilde{Y}_i^{(t)} + P_i^{(t)}))$, $\exp(\operatorname{arctg} \theta(B_i + \frac{\partial}{\partial s_i}))$, $\exp(\theta(T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}))$. 所以, $\exp(\tilde{y}(D(v_N, F)))$ 以 $\exp(\theta(X_{ij}^{(t)} - Z_{ij}^{(t)}))$ 为生成元, $\exp(\tilde{L}_1)$ 以 $\exp(\theta(Y_i^{(t)} - \tilde{P}_i^{(t)}))$, $\exp(\theta(\tilde{Y}_i^{(t)} + P_i^{(t)}))$ 为生成元, $\exp(\tilde{L}_2)$ 以 $\exp(\operatorname{arctg} \theta(B_i + \frac{\partial}{\partial s_i}))$, $\exp(\theta(T_{ij}^{(t)} + 2\frac{\partial}{\partial z_{ij}^{(t)}}))$ 为生成元. 至此完成了定理的证明.

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